

R·I·T

DIRSIG Models to Support LDCM

Digital Imaging and Remote Sensing Laboratory
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John R. Schott

<http://dirsig.cis.rit.edu>



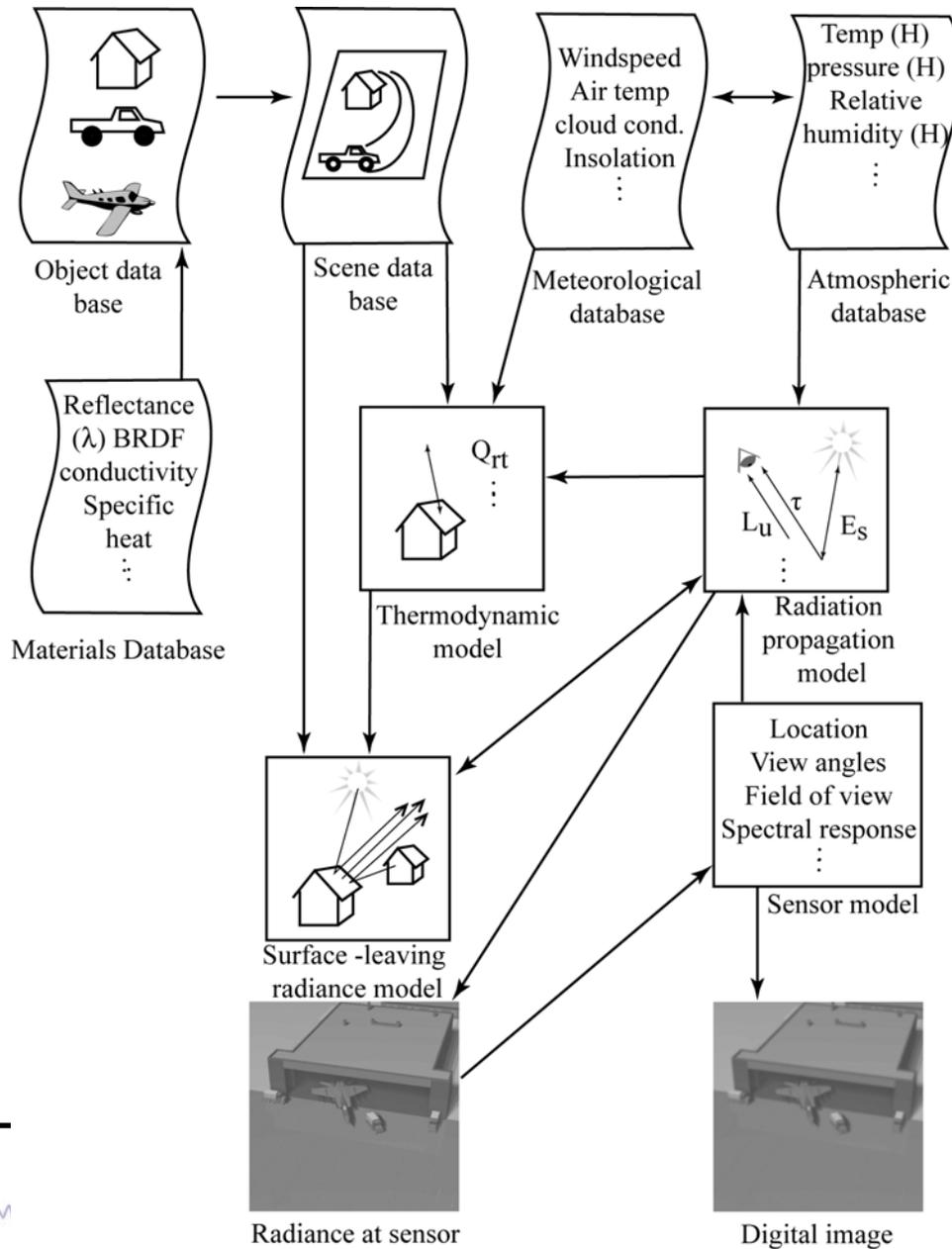


Figure 14.2

Diagram of conceptual data flow and interaction mechanisms in a generic SIG model.

Section 14.3 A Modeling Example

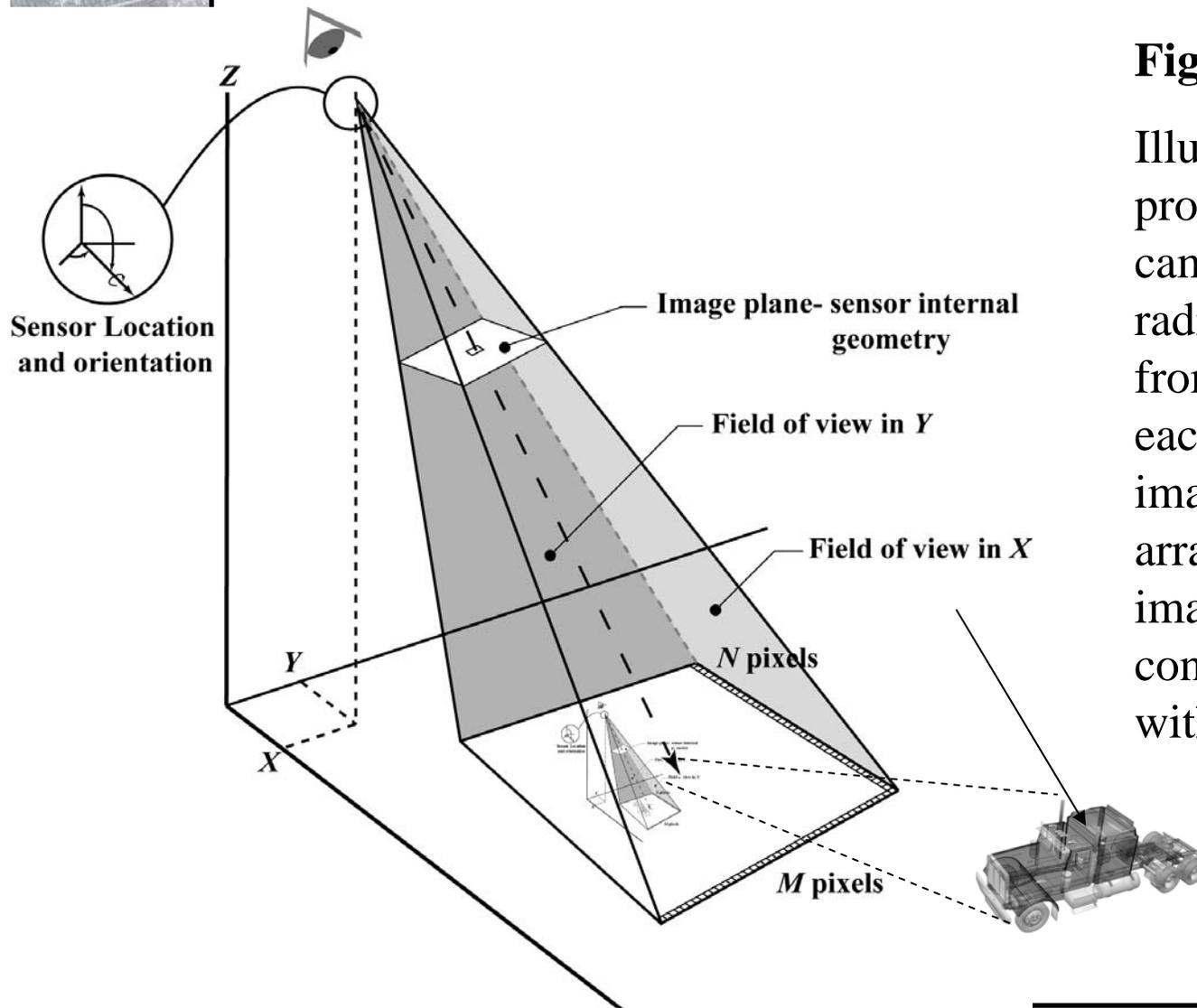


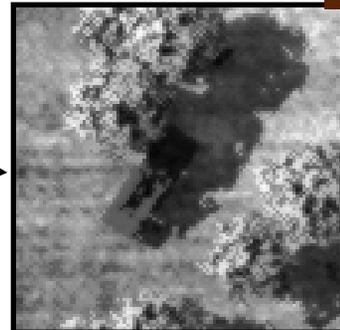
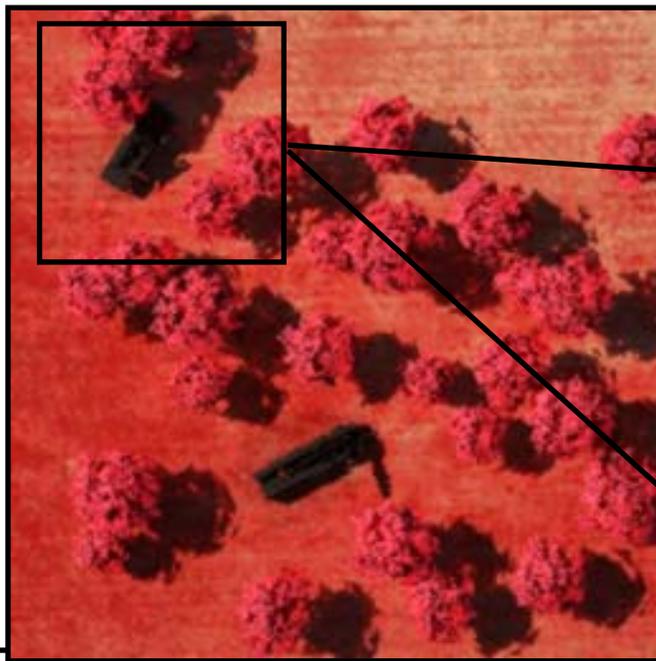
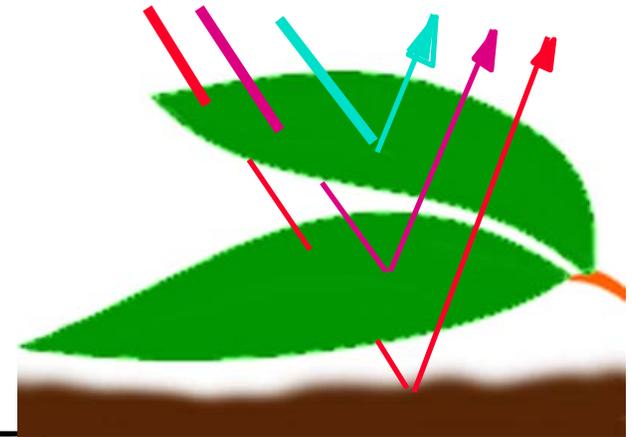
Figure 14.9

Illustration of the ray-tracing process for a simple framing camera. To generate an $N \times M$ radiance array, rays are traced from the focal point through each pixel center in an $N \times M$ image plane. Note the $N \times M$ array is denser than the final image array to allow convolution and resampling with the instrument PSF.

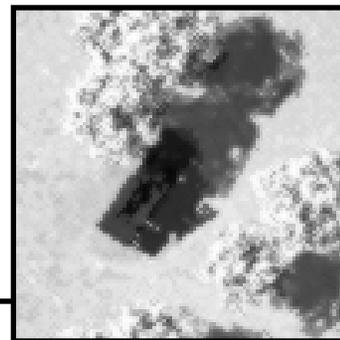


Forestry

- The model includes the transmission of leaves to reproduce the complex energy exchange in tree canopies.

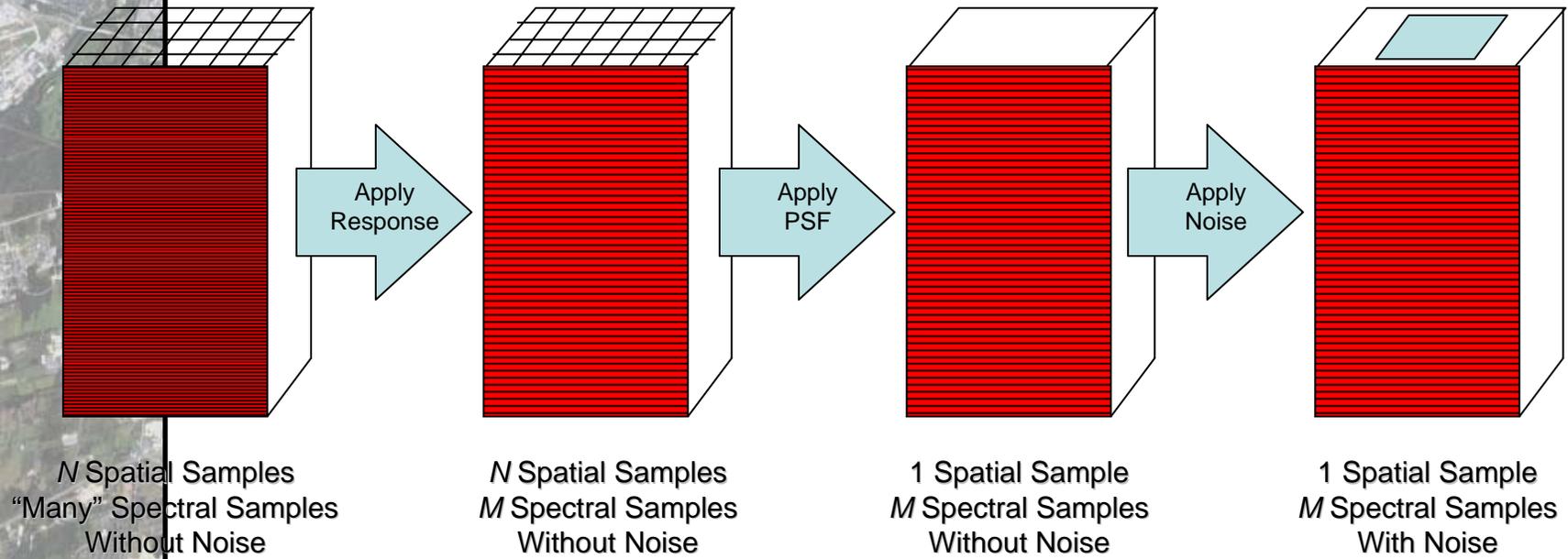


Green Band

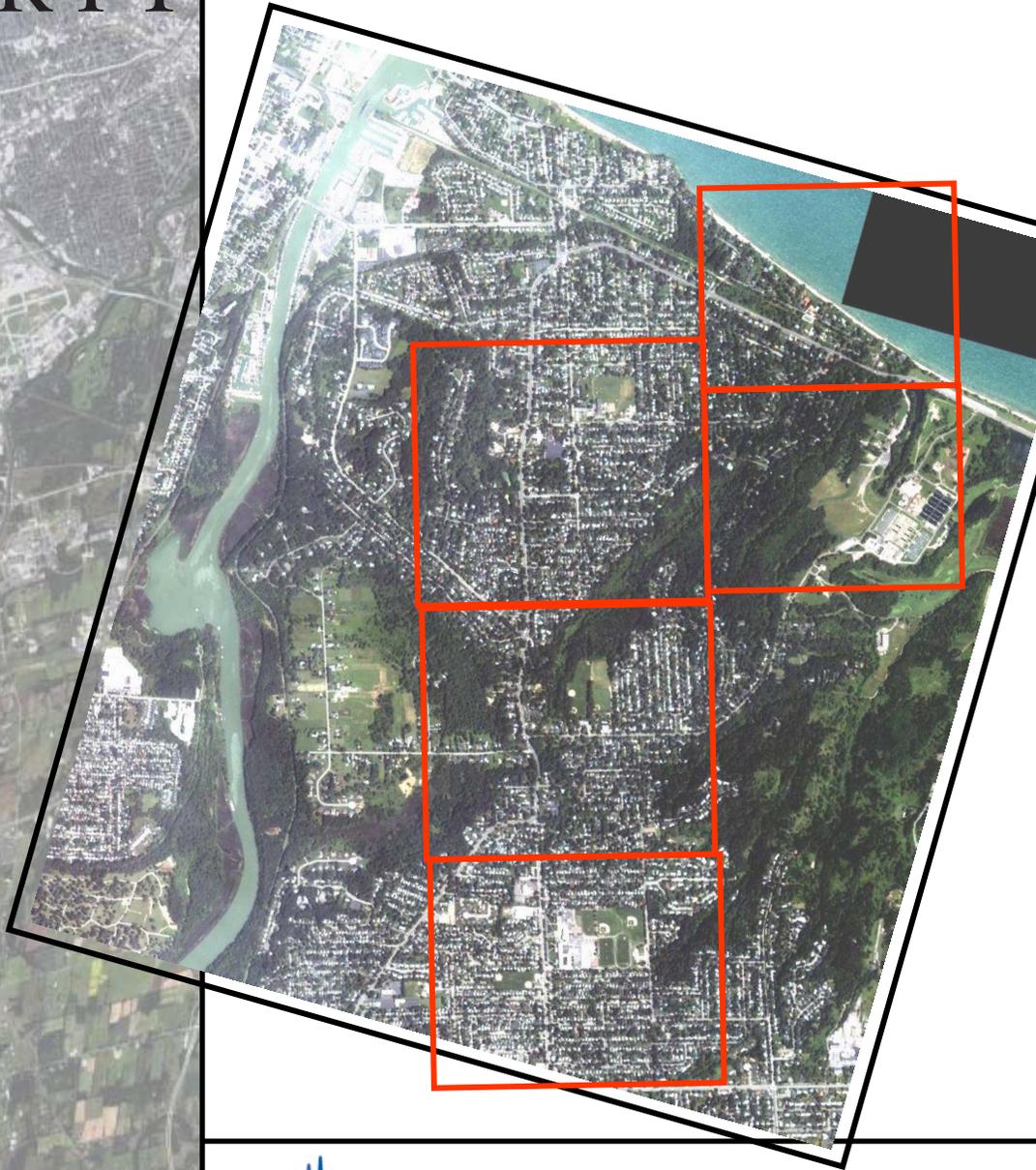


NIR Band

Internal Data Flow



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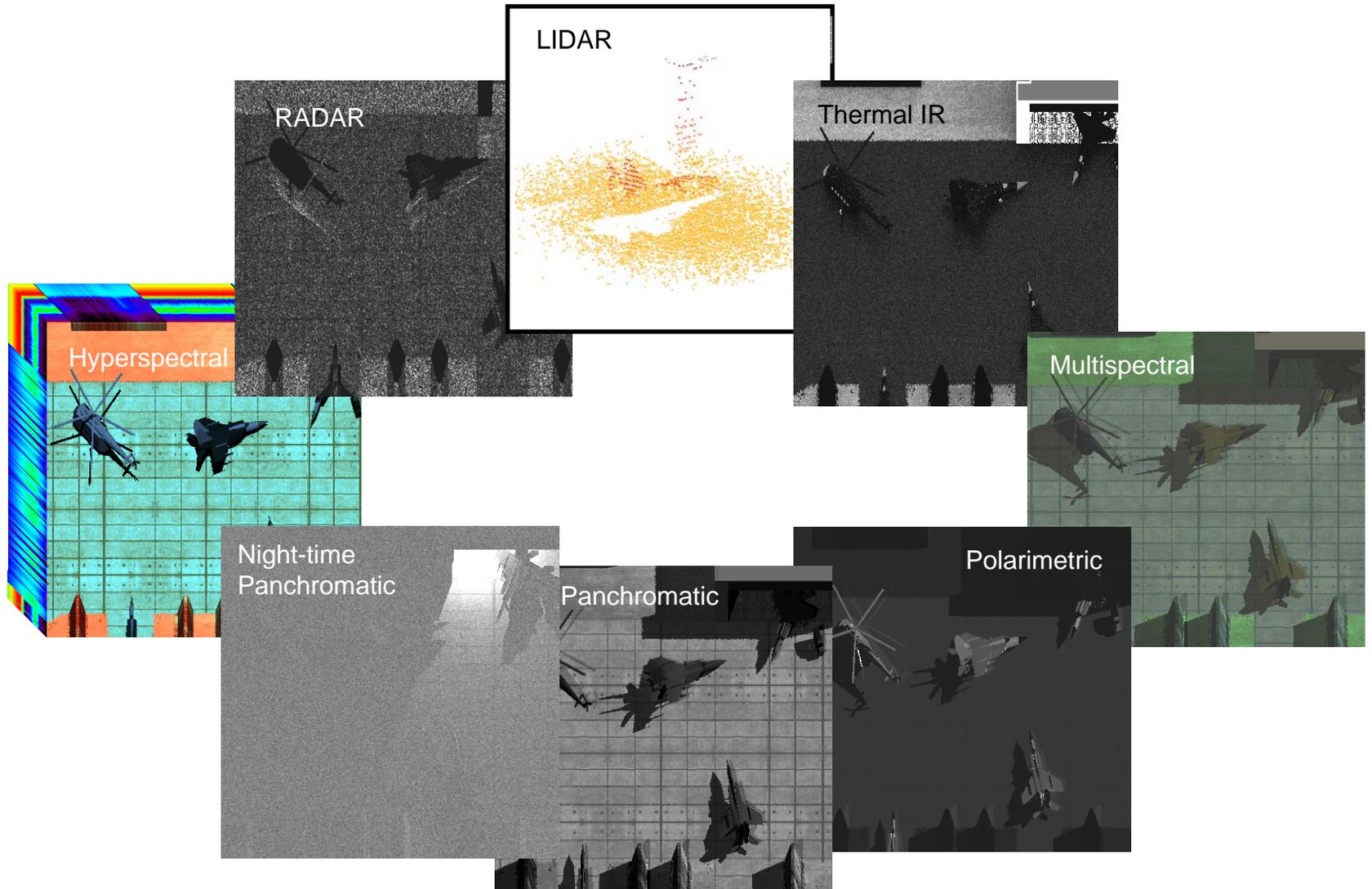


Megascene 1, Tile 1



- 5,000+ objects
- 500+ million facets
- 1.6 km² (0.6 mi²)

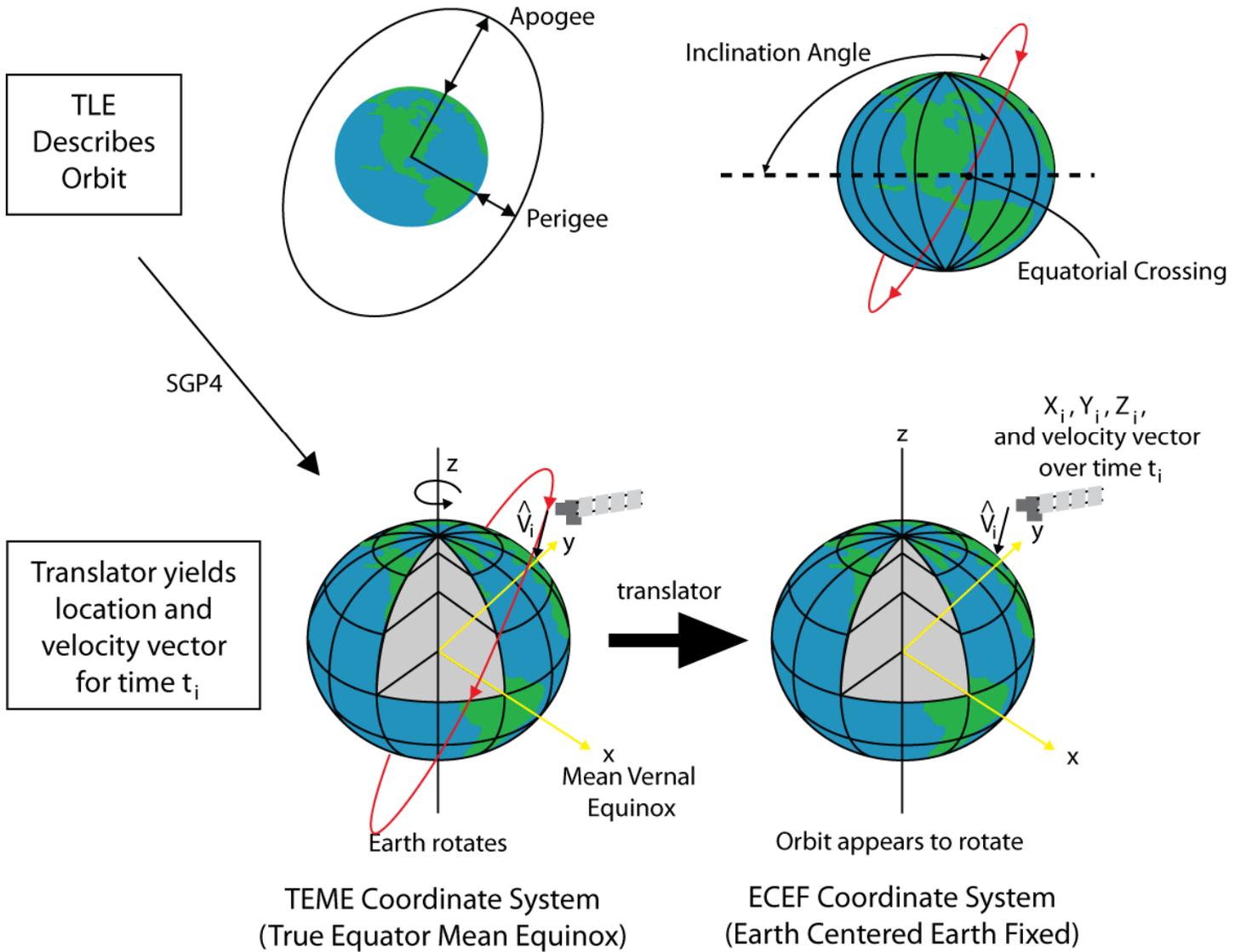
One model, many modalities

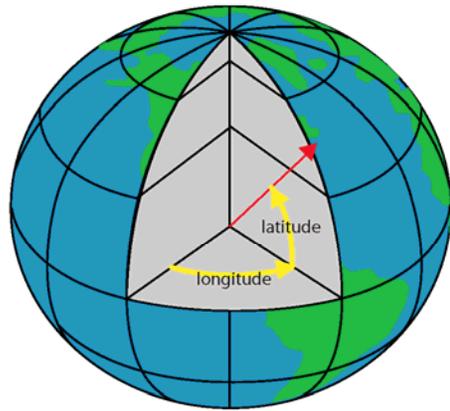


Approach

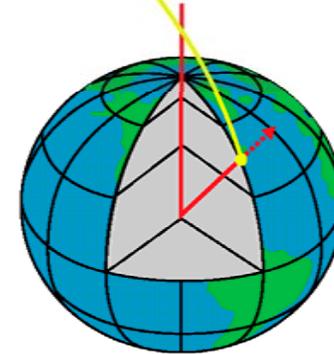
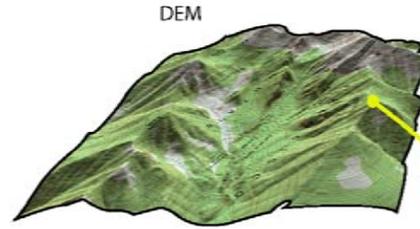
- Use DIRSIG to model OLI/TIRS imaging capabilities
 - Geometric effects top priority
 - Radiometry in future revisions
- Use fused data sets to establish **virtual truth**
 - Digital Globe
 - Hyperion
 - LANDSAT
 - DEMs
 - ASTER emissivity maps

TLE → Orbital Descriptors → SGP4 Translator → TEME → TEME to ECEF Translator → ECEF

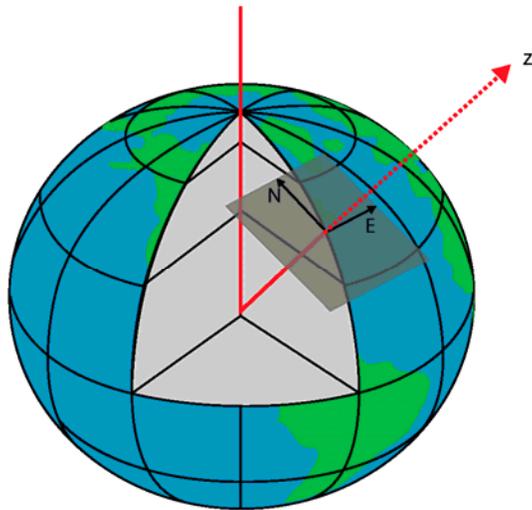




Angle, angle, distance describes any point on the surface.



DEM is height above or below WGS 84.



DIRSIG NATIVE Format is Euclidian with x,y plane tangent to Earth.

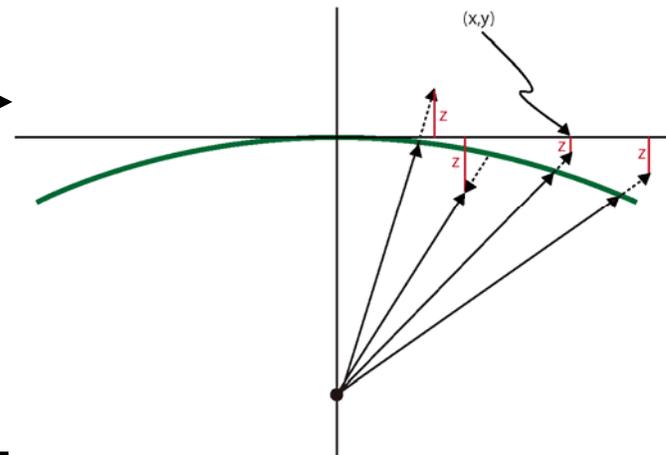
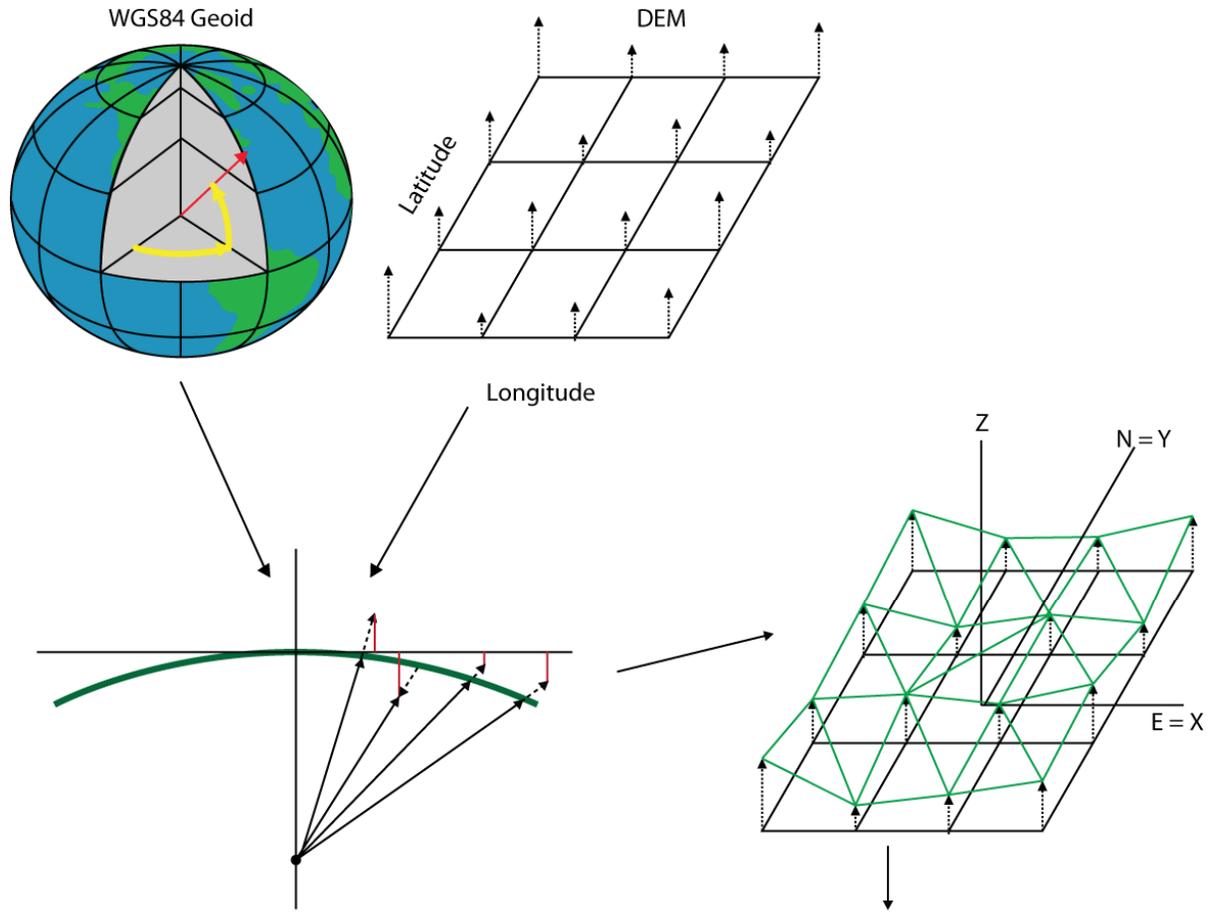


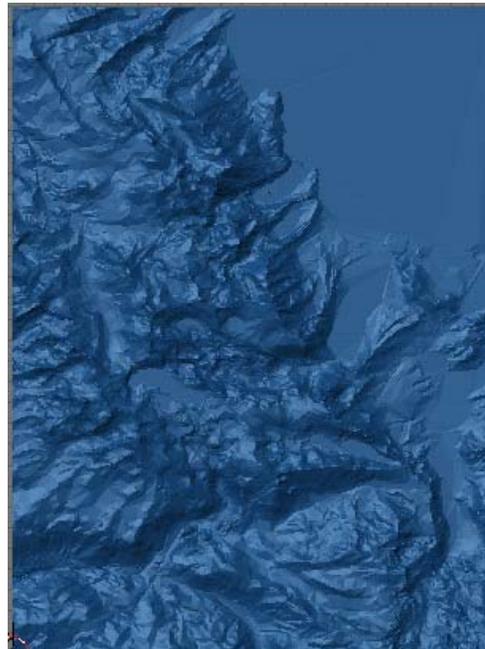
Illustration of how angle, angle, distance (DEM) is converted to NATIVE DIRSIG geometry.



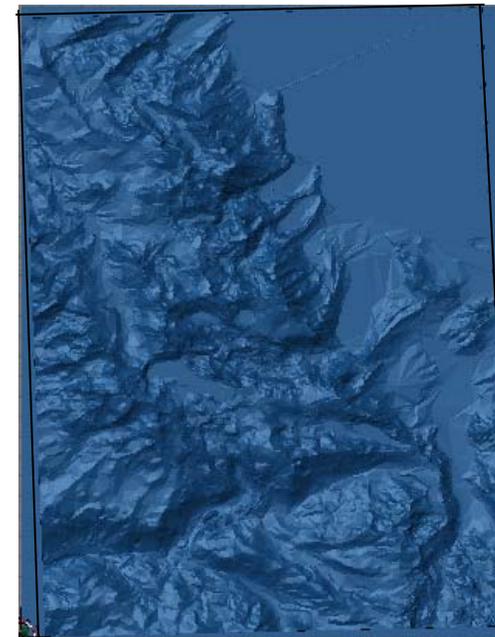
Orbitology Path Forward

- We are building the translators and will be writing code to format the data into DIRSIG standard format and then testing in DIRSIG.
- At some point, the DIRSIG user interface could be adjusted to facilitate use of this approach. E.g., select satellite, date and time and the code would go out on WEB and get TLE and run code for that satellite.

Status: Most Component tools in test



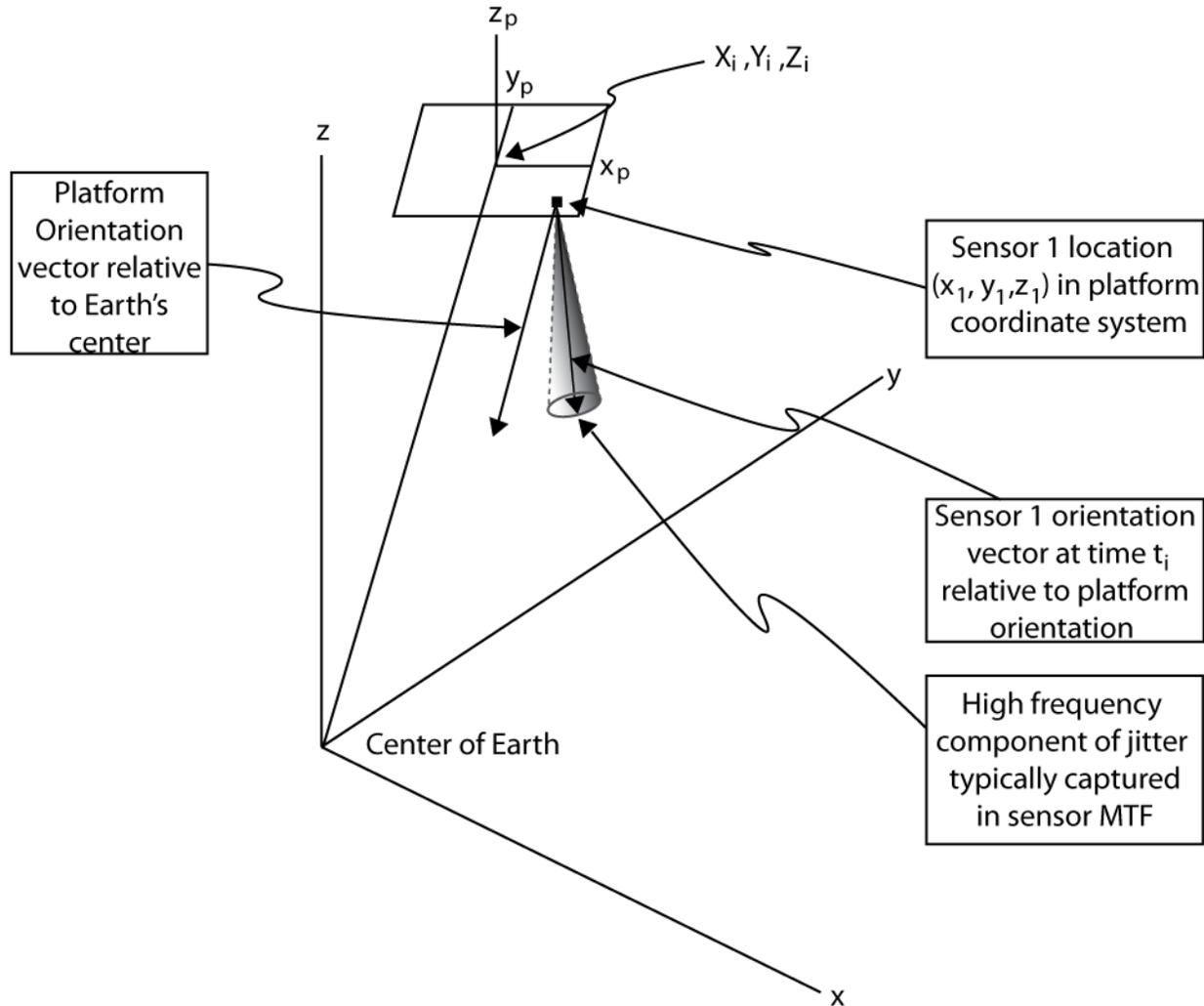
DEM in Lat. Long



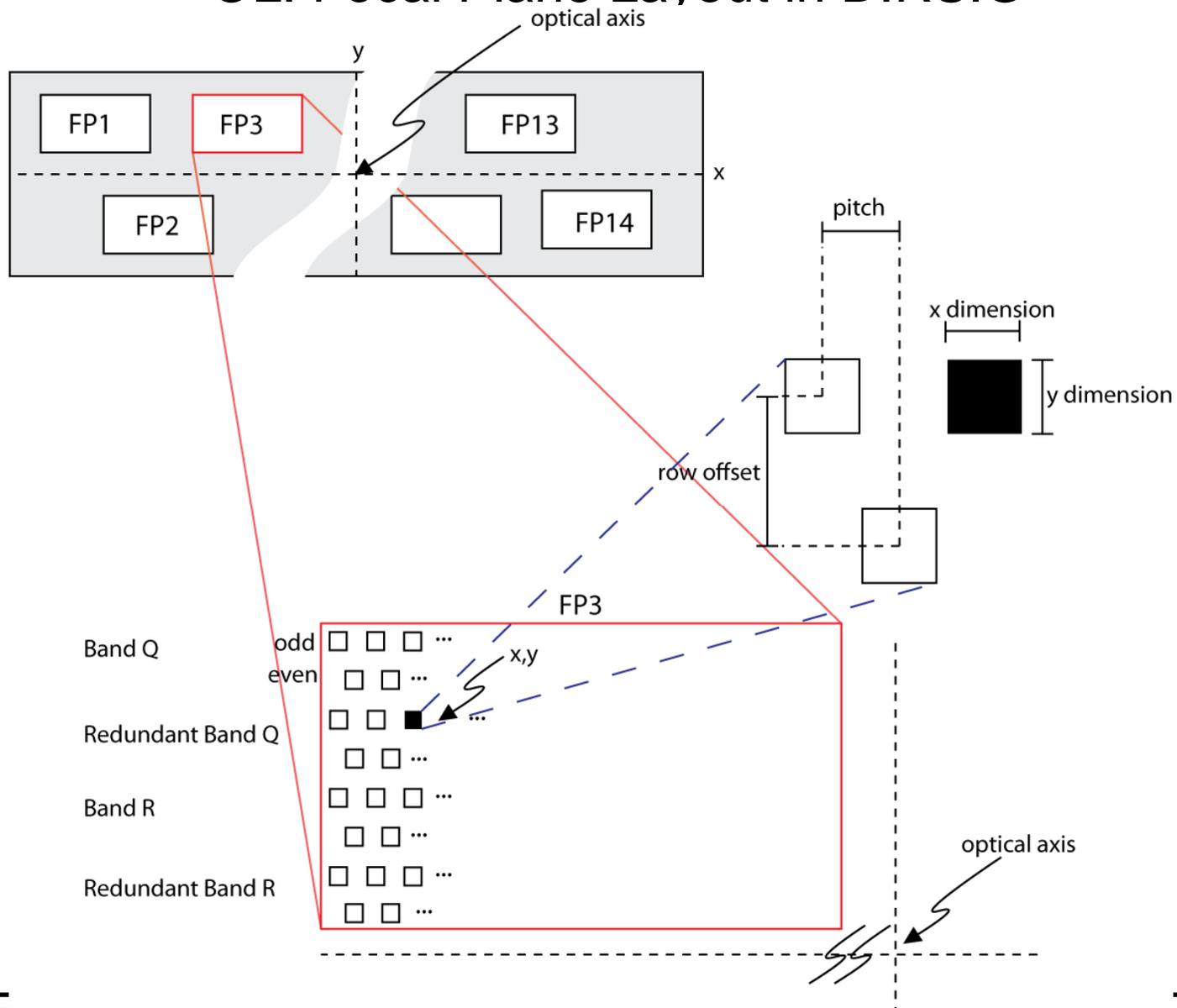
DEM in UTM

In Bulldozer

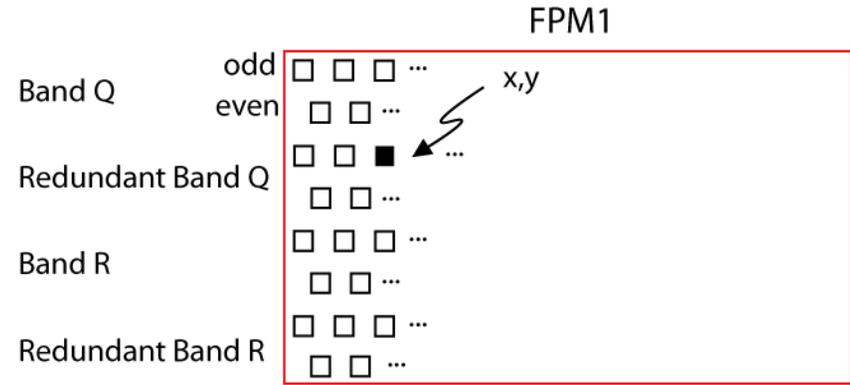
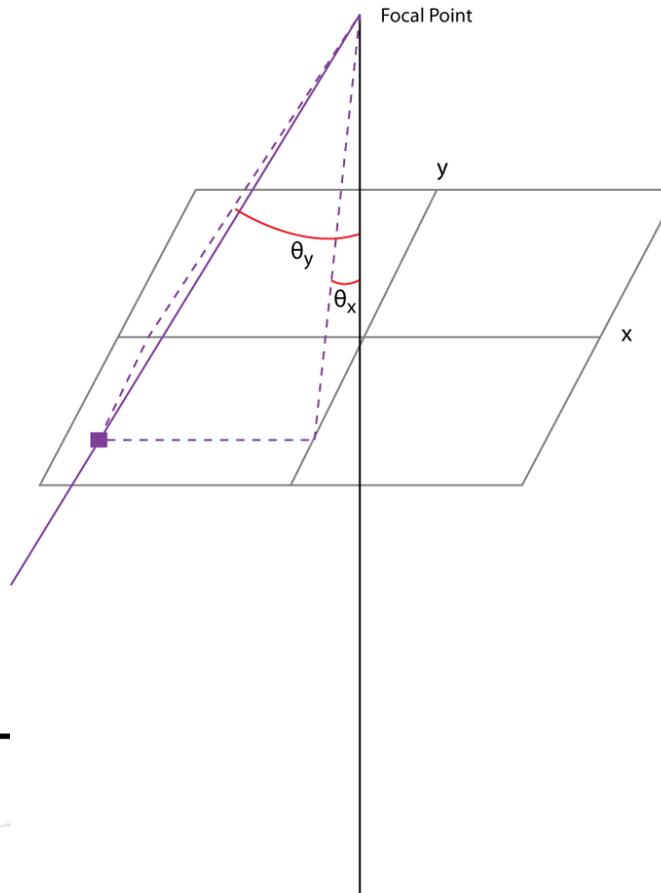
DIRSIG Platform/Sensor Model



OLI Focal Plane Layout in DIRSIG



Pixel locations are designated by angle pairs accessed by a user controlled look-up-table



Focal Plane Module	Band	Primary/Redundant	Odd/Even	Detector
1	1	Primary	Odd	1
1	1	Redundant	Even	1
1	1	Primary	Odd	2

↓
Look Up Table
↓

Designator	θ_x	θ_y
11P01	0.0071	0.0072
11P02	0.0076	0.0076
11P03	0.0072	0.0074

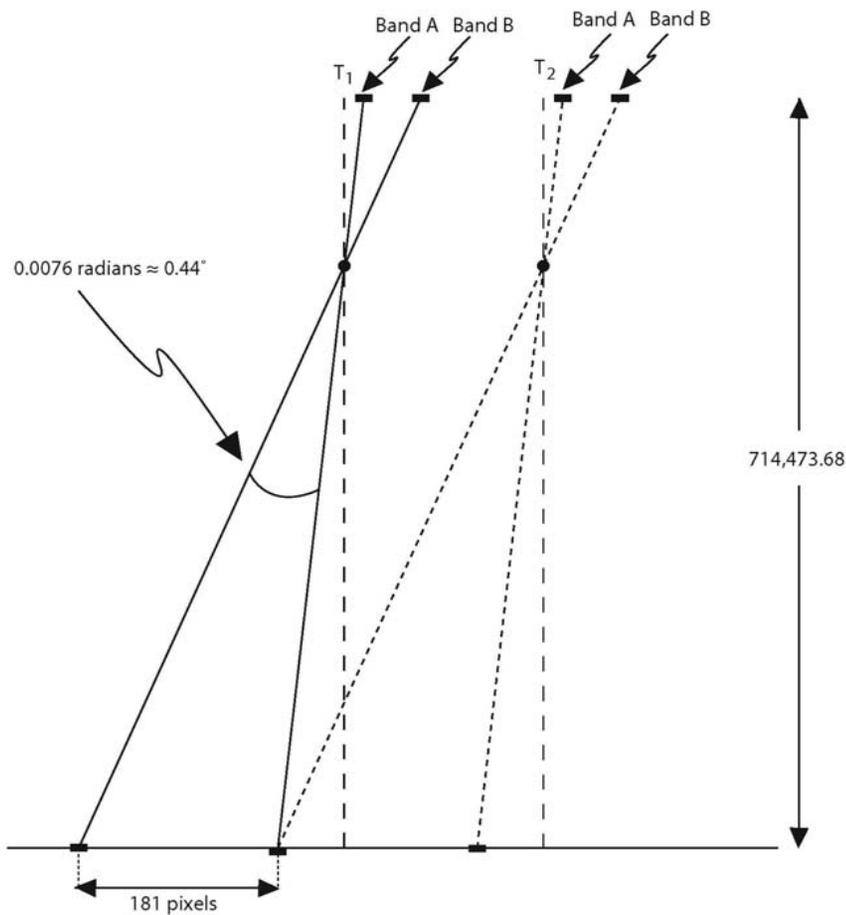


Figure 1: At nominal flying height (AGL) Bands A and B require 181.0 pixels of offset to exactly register A to B.

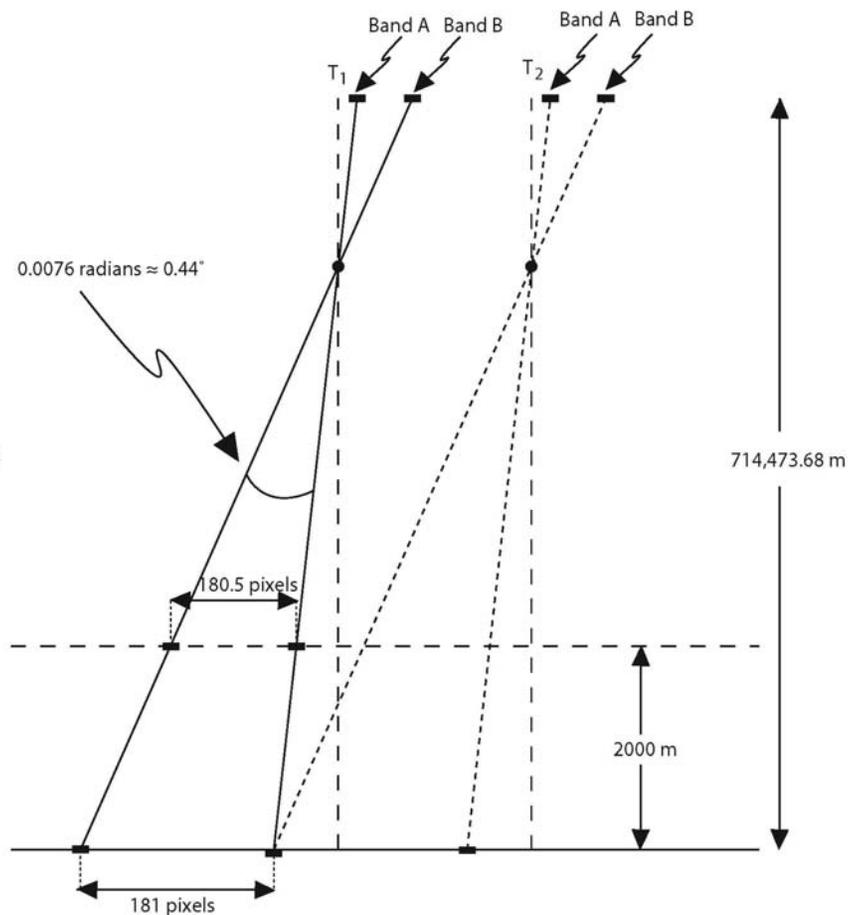
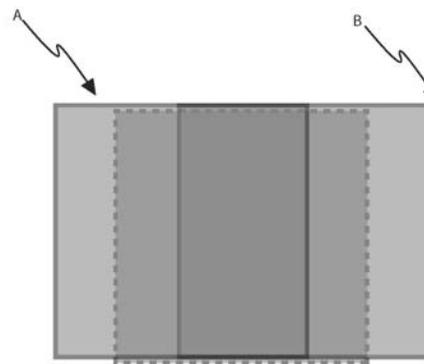
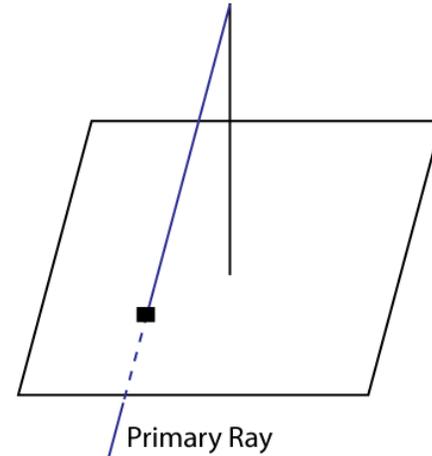


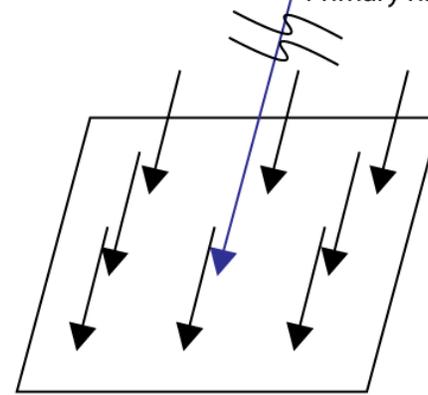
Figure 2: For a target at 2000m AGL Bands A and B are offset by 180.5 pixels



Primary ray defined by detector element angle-angle designation

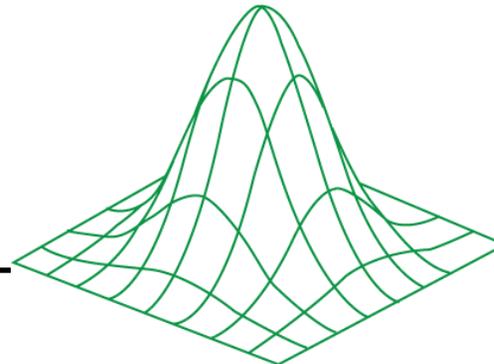


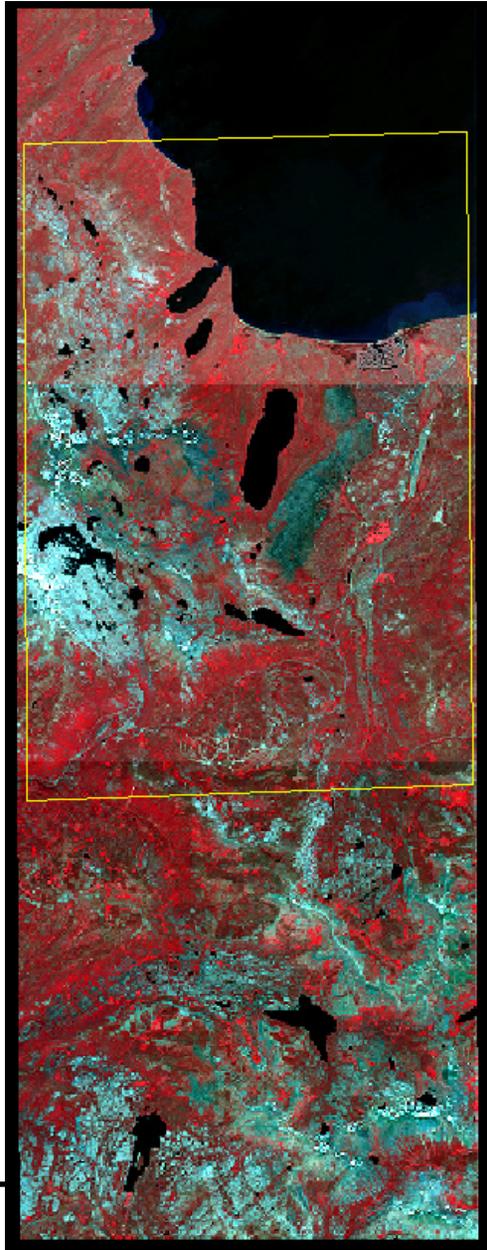
User defined level of oversampling about primary ray



*

Convolution of oversampled radiance values with band specific or focal plane array specific instrument PSF





Quickbird 4 band MSI

Sensor: Tahoe Area

AcqDate: Jun 28, 2007 Sensor: QB02

Format: NITF

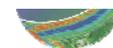
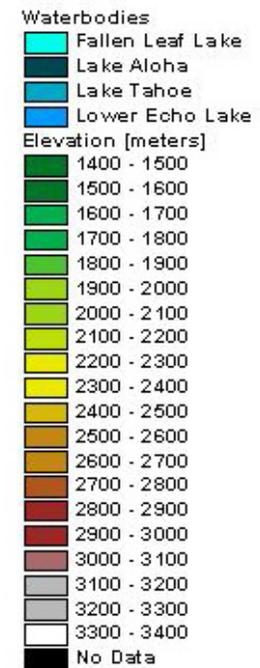
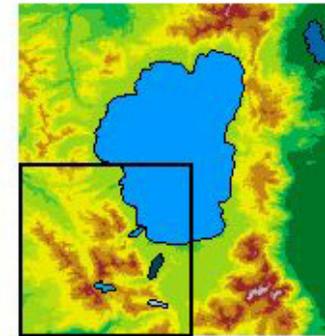
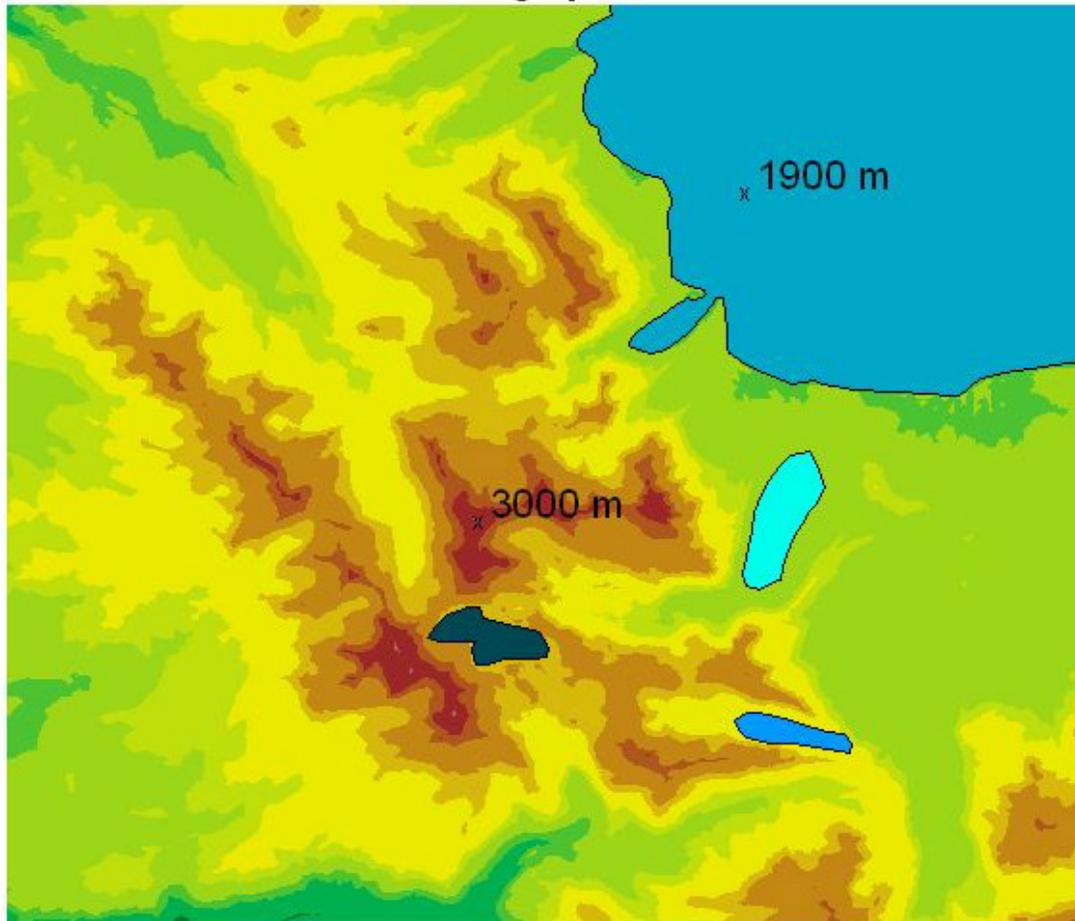
Geo-spatial: Geographic WGS84

QB Dimensions: 17km x 47km
compared to 30m pixel * 500
detectors = 15km



Lake Tahoe Area Elevation [meters]

National Elevation Dataset (NED) 1/3 Arc Second
X Y cell size ~10 meters or 0.00009 Degrees
NAD Geographic

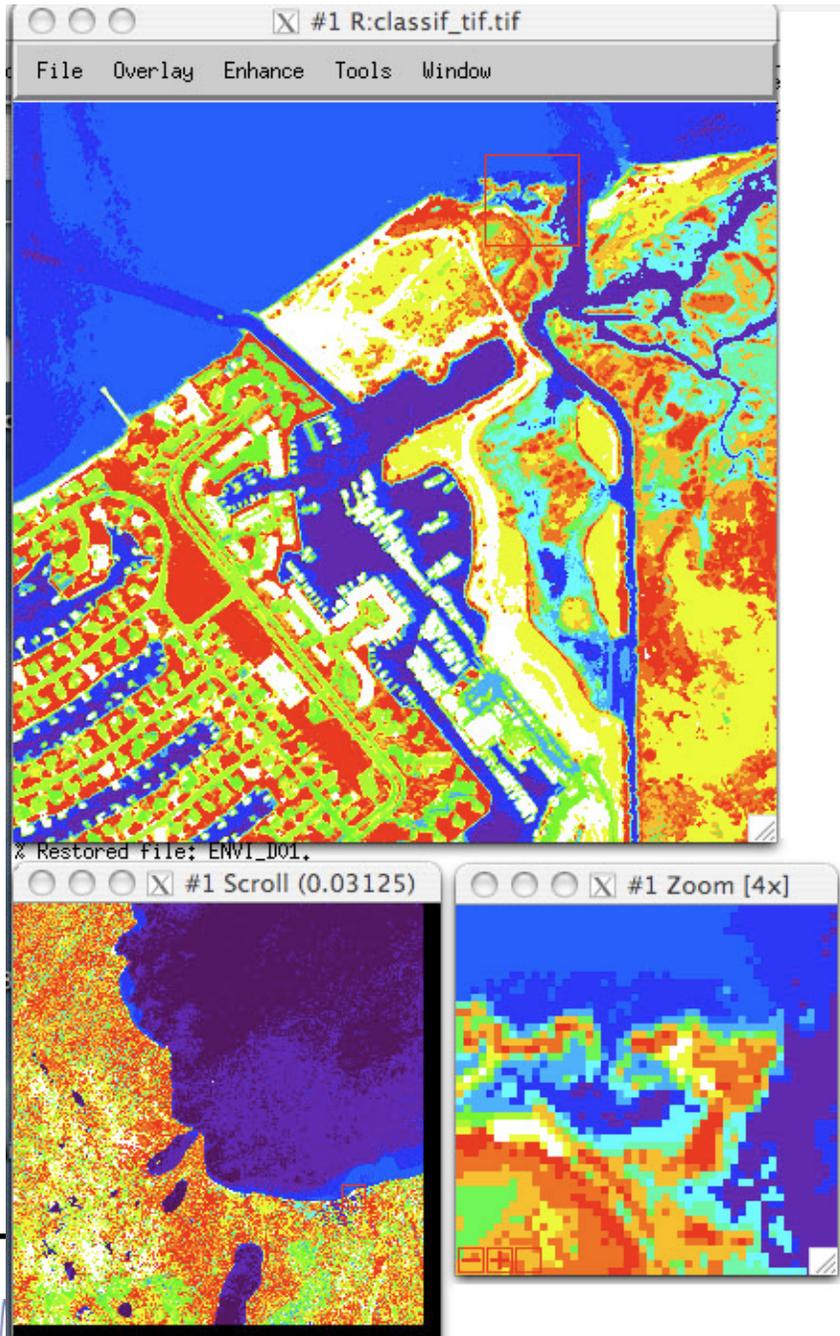


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EO1 Hyperion Scene

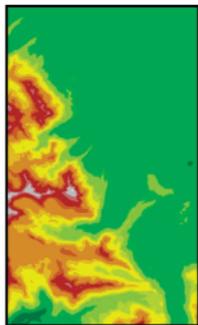




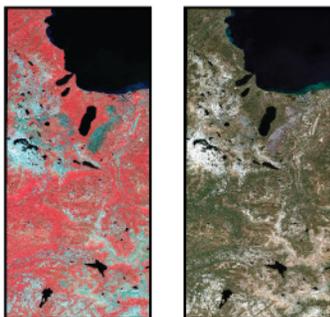
Example Quickbird
Unsupervised Classification
(Isodata)
15 bands



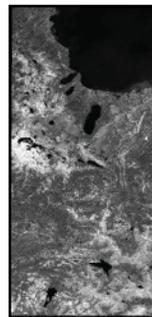
DEM



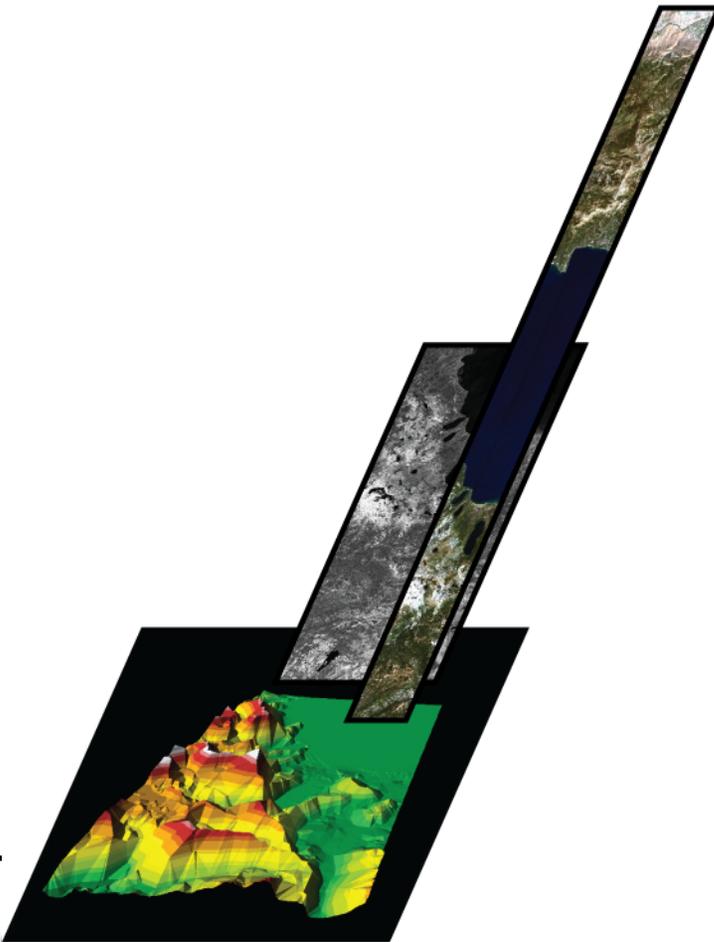
Digital Globe



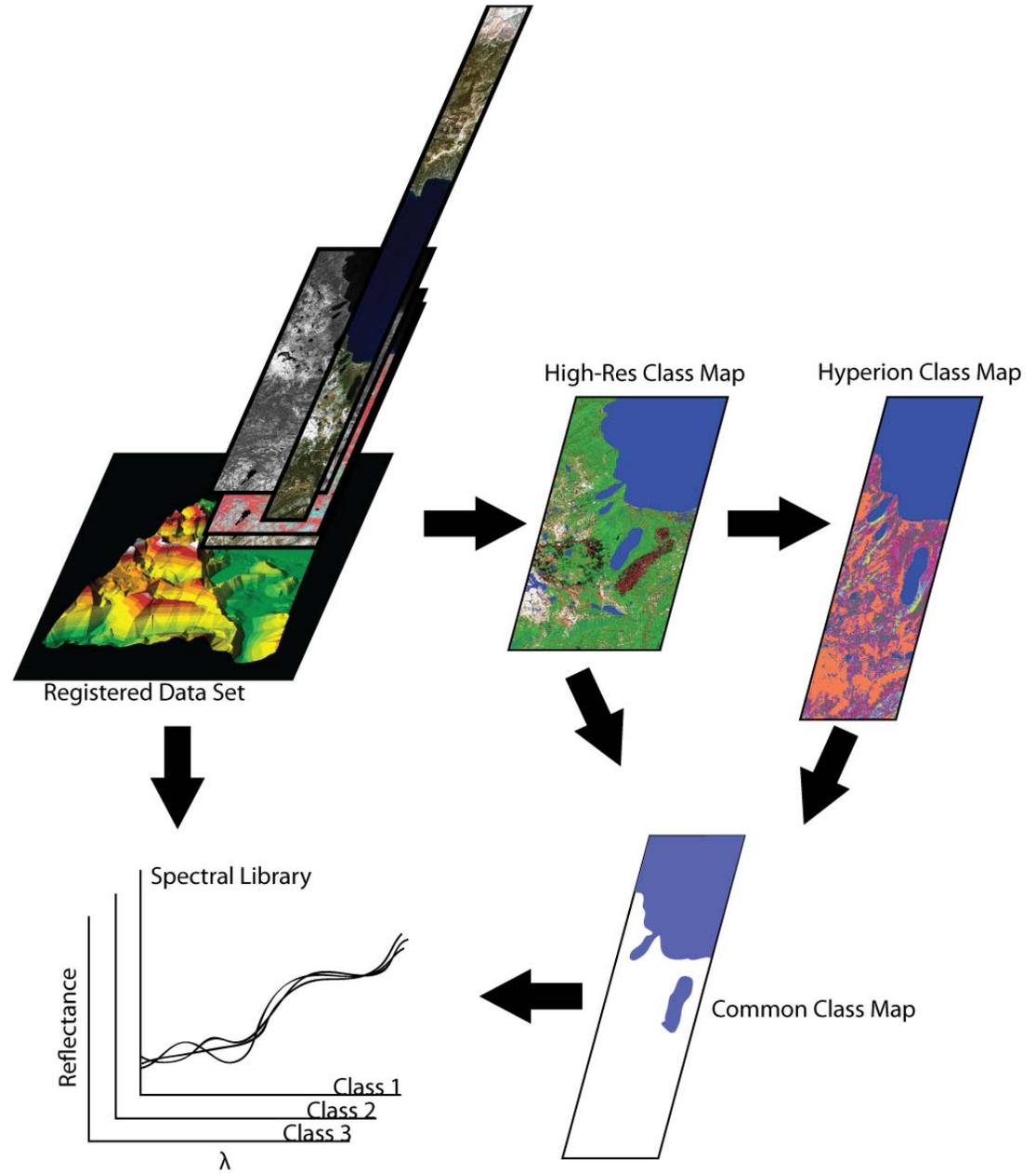
ASTER



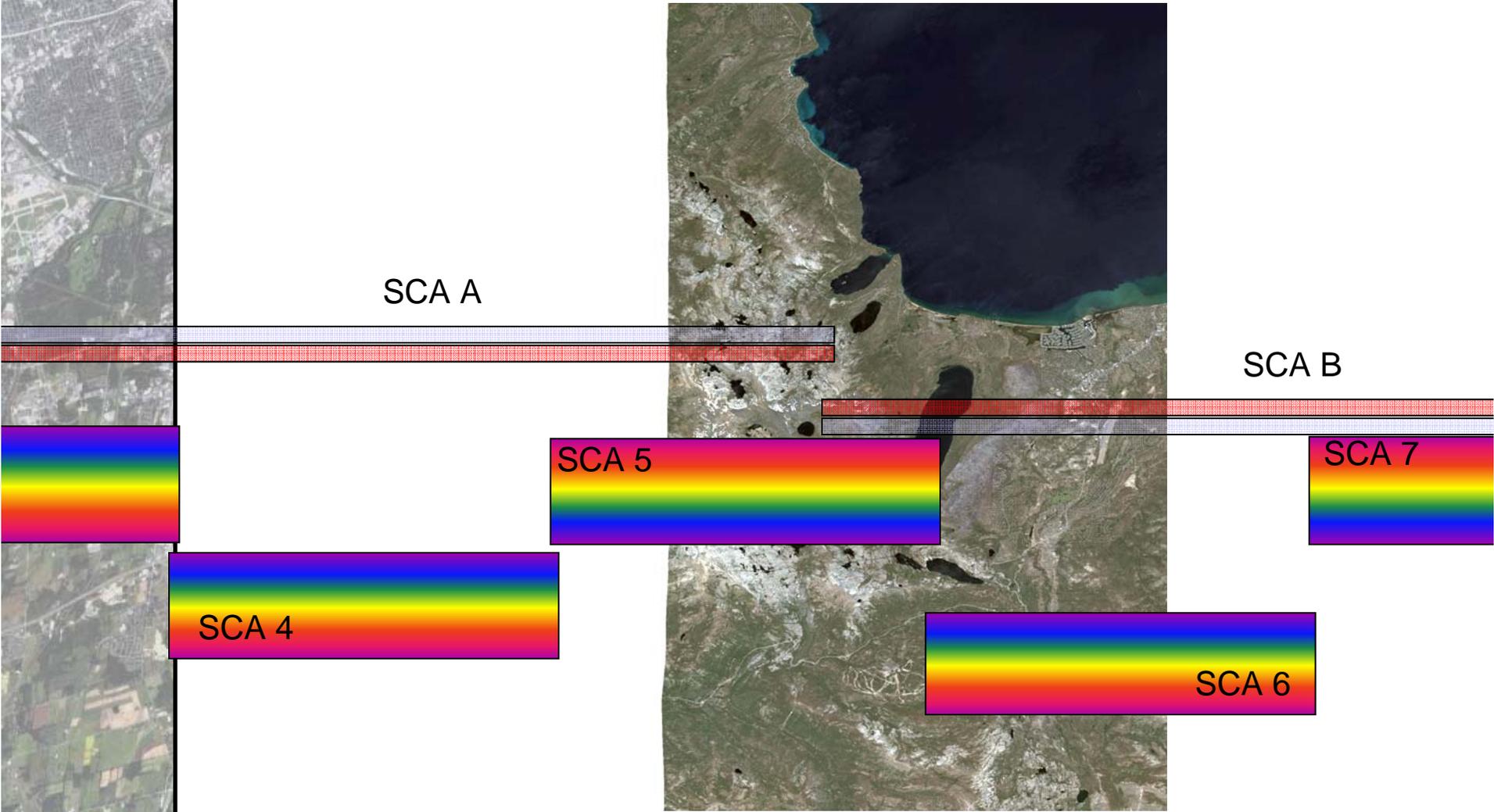
Hyperion



Registered Data Set



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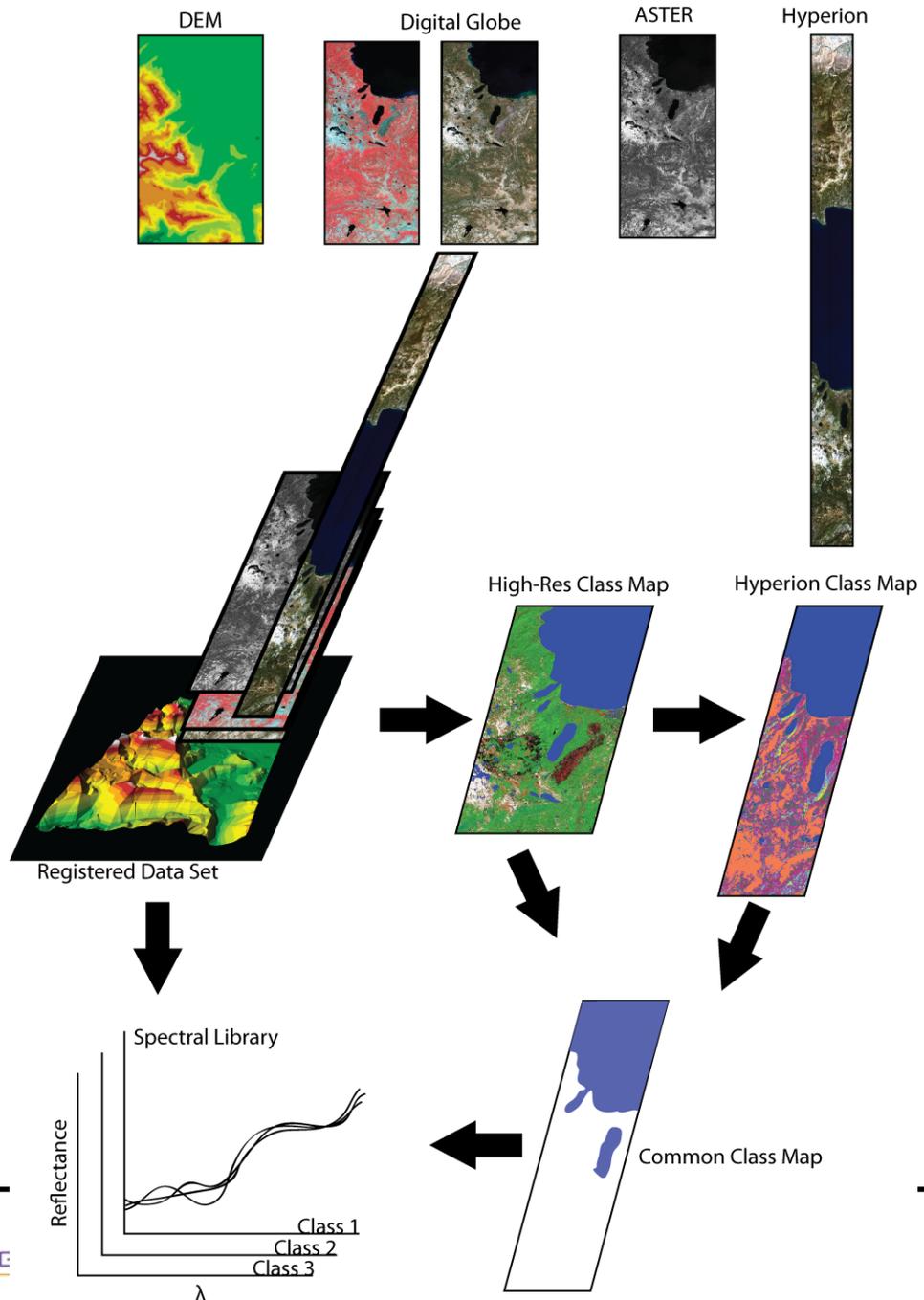


SPIRAL 1

- Internal goal is first release at six months: End Feb 2010
 - First OLI image
 - Orbital Geometry
 - Angular detector location
- Plan to release first TIRS image approximately six weeks later
 - Per class bulk properties

Spiral development approach will allow updates on a regular basis (roughly every six months). Each release will improve sensor and scene fidelity.

- <http://dirsig.cis.rit.edu>



Scene Creation

- Status: Quickbird data registered to DEM and Initial Class Map Generated
- Working on EO-1 Registration
- Soon!!! ELM calibration of EO-1.Later!!!Per Pixel Atmospheric Compensation and Class Attribution.

Path Forward (Post rev 1)

- Convert Hyperion images to reflectance using ELM fits to reflectance estimates of multiple photo interpreted targets
- Reprocess radiance spectral databases to reflectance
- Allow DIRSIG to model atmosphere and illumination
- Develop methods to incorporate thermal effects

Short Term Thermal

- Assign thermal materials properties by class based on photo interpretation of class type and thermodynamic databases
 - Emissivity spectra (ASTER maps?)
 - Specific heat
 - Conductivity
 - Density
 - Thickness

Short Term Thermal

- Assign absorption, slope, aspect from DIRSIG knowledge of $r(\lambda)$ and DEM
- Tune bulk properties by class using Therm estimates of mean behavior compared to Landsat ETM+ derived temperatures for a range of dates

Long Term Thermal

- Input weather to Therm for 24 hours before Landsat acquisition
- Get absorption from Hyperion spectra
- Slope and aspect from DEM
- from material type (Note this requires manual determination of class name of unsupervised classes and assignment of emissivity spectra)
 - Alternately, does ASTER have viable emissivity product?

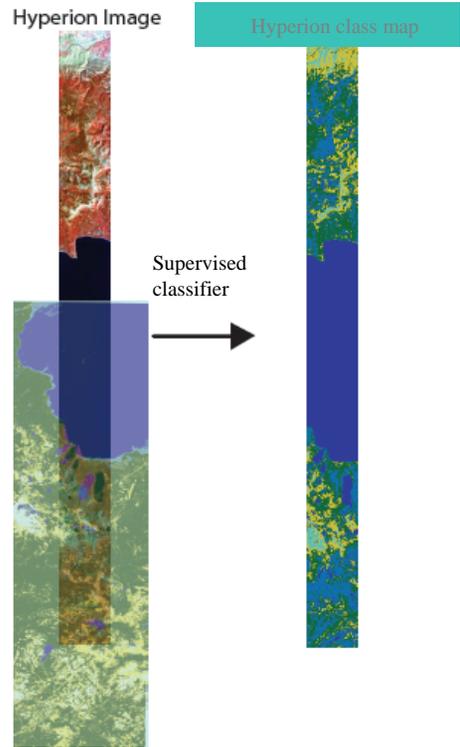
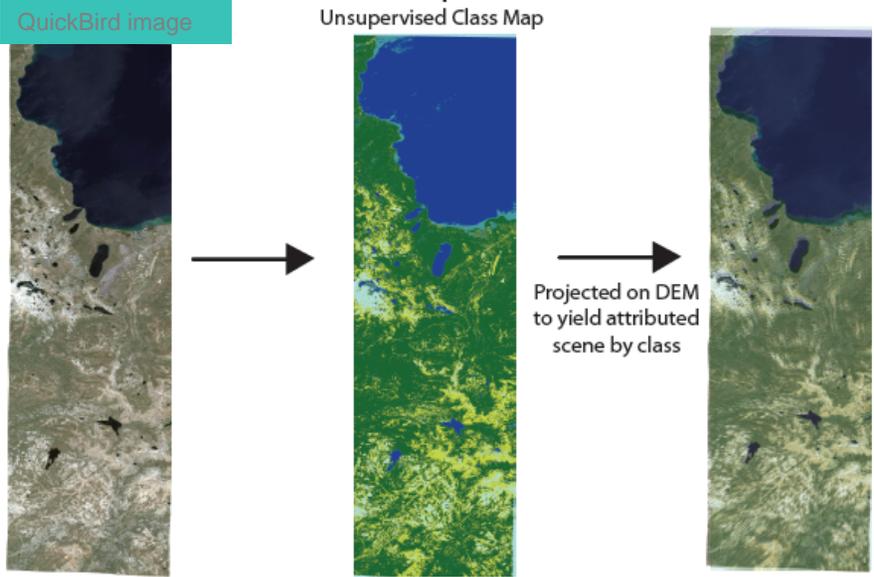
ε

Long Term Thermal

- For registered pixels in study region at ETM+ resolution calculate surface leaving radiance and apparent temperature for 5 or more days
- With inputs described above – vary remaining 2 free parameters in Therm to obtain best estimate of these parameters on a per pixel basis



Data Preparation



Section 14.3 A Modeling Example

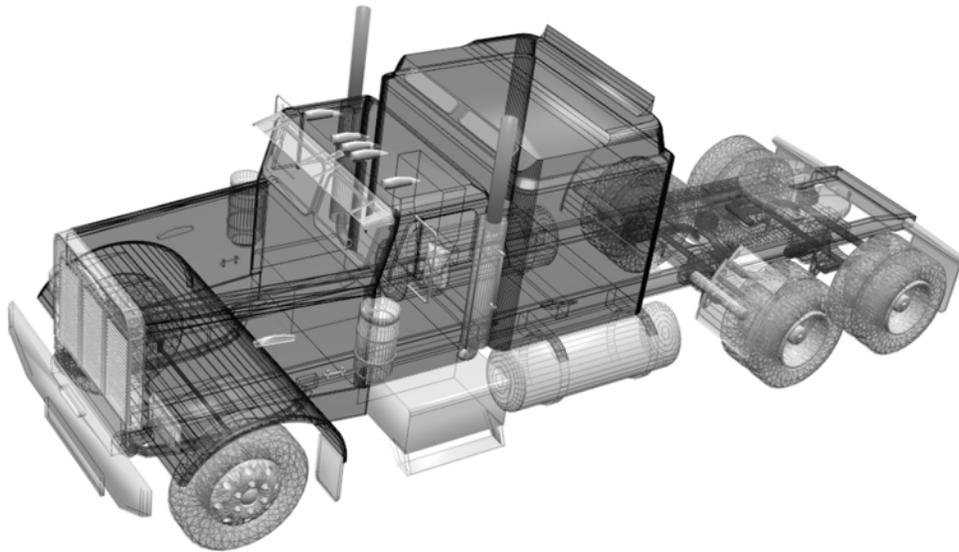
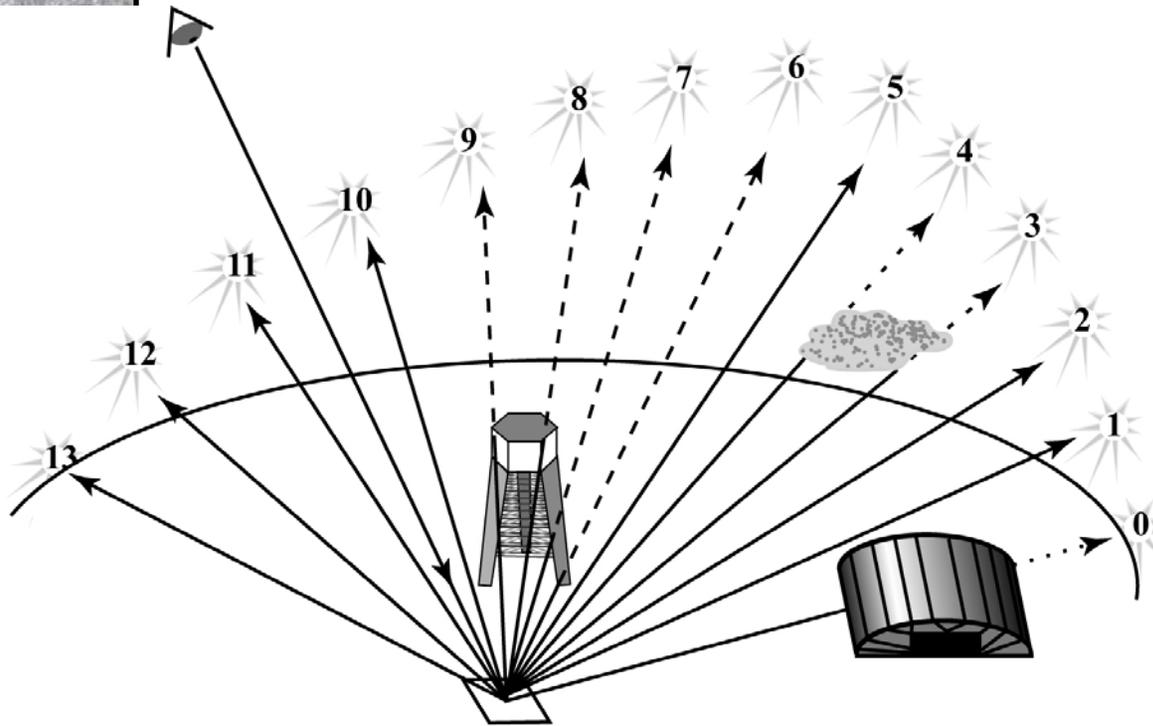


Figure 14.7

Wire frame of an object used in the SIG process. The object is produced using CAD software and material types are assigned to each facet during the construction process.

Section 14.3 A Modeling Example

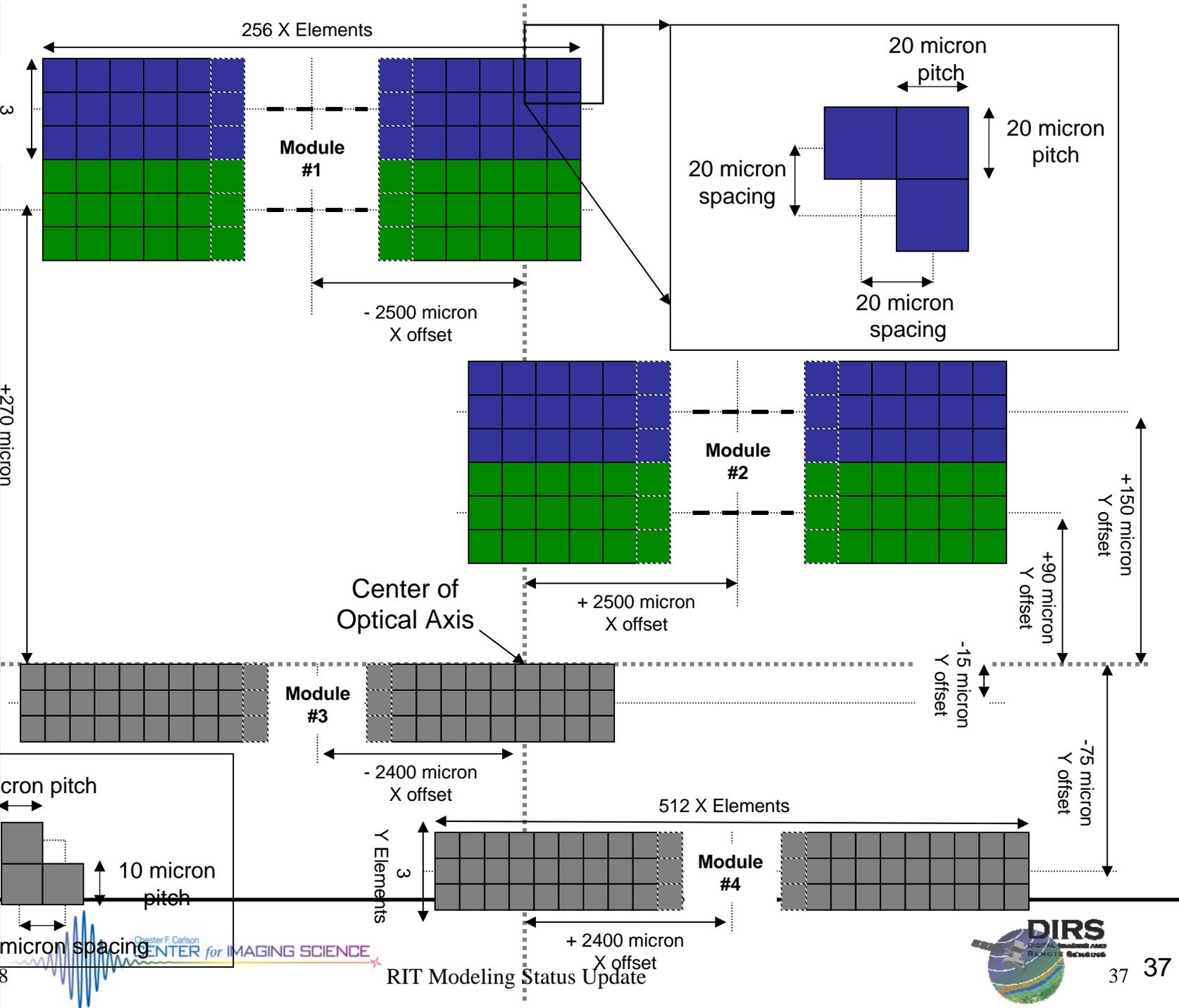


0.0	1.0	1.0	0.4	0.23	1.0	0.0	0.0	0.0	0.0	1.0	1.0	1.0	1.0
0	1	2	3	4	5	6	7	8	9	10	11	12	13

(total shadow) 0.0 < direct insolation modifier < 1.0 (total sunlight)

Figure 14.10

Sun shadow history,
including partial
obscuration by
transmissive objects.



12-Nov-2008

Center for IMAGING SCIENCE

RIT Modeling Status Update



Megascene 1

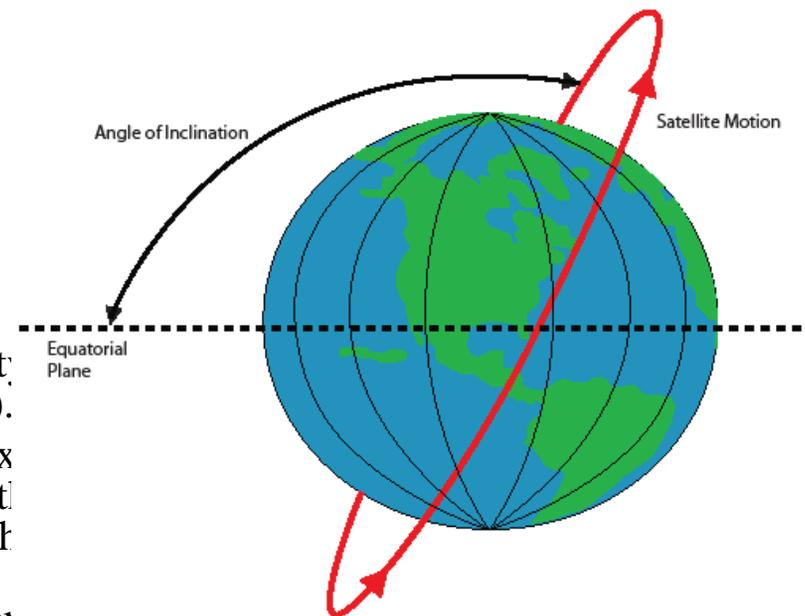
Thermal Infrared

- Complete VIS-NIR coverage
- MWIR coverage
 - RIT lab measurements for hard objects
 - Database for natural objects
- LWIR coverage for most objects
 - RIT measured and available databases
 - Updating and expanding



Orbitology Path Forward

- Uses the NORAD Two-Line Element (TLE) format for describing the Orbit (Keplerian Elements). This is information on Inclination, Eccentricity, Drag, etc.). TLE are readily available for all NASA satellites (Note they are updated regularly (e.g., weekly) to adjust for orbital perturbations).
- Feed DIRSIG satellite TLE, start time, end time and sample clock rate.
- Use SpaceCom's Simplified General Perturbations version 4 (SGP4) orbital propagator to convert to position and velocity for any given time (we use SGP4-Celestrak).
- Output is in True Equator and mean Equinox (TEME) format . We need to convert to Earth Centered-Earth Fixed (ECEF) format. (North =z, sun at Noon on vernal Equinox is x and right hand rule yields y). Note that the vector from the location x, y, z to the origin (Earth's center) is the nominal line of sight (LoS) of the instrument. Finally we convert to DIRSIG's native East North Up (ENU) format.



Sensor Design

Implementation Plan is to Use Actual Sensor Angle-Angle descriptors of Detector Element Effective Focal Plane Location and a LUT to Relate Active Detectors and Sample Order to Tabulated Angle-Angle Data (**Status: Scripts are in place and under test**)

Angle-Angle Detector Locations

SCA	Band	Set	Detector	X	Y
1	1	1	1	0.0064828	0.1345405
1	1	1	2	0.0065670	0.1344997
1	1	1	3	0.0064800	0.1344587
1	1	1	4	0.0065641	0.1344179
1	1	1	5	0.0064771	0.1343768
1	1	1	6	0.0065612	0.1343360
1	1	1	7	0.0064743	0.1342950
1	1	1	8	0.0065584	0.1342542
1	1	1	9	0.0064714	0.1342131
1	1	1	10	0.0065555	0.1341723
1	1	1	11	0.0064686	0.1341312



Sensor Design

Detector Element Spatial Sampling

Simple Capture

Spectral Response Spatial Response Output

Use delta function sampling (output a single sample per pixel)

Use an oversampling factor (output multiple samples per pixel)

Samples x

Use a spectrally constant point spread function (PSF)

Samples x

Shape

Pixel Footprint

Sensor Design

Detector Spectral Response

Simple Capture

Spectral Response | Spatial Response | Output

Channel List

Channel #1

Channel Description

Name: Channel #1

Type: Tabulated Data

	1	2
1	14000.000	-8.9900E-06
2	14500.000	2.4300E-05
3	15000.000	1.1009E-04
4	15500.000	3.3358E-04
5	16000.000	5.2780E-04
6	16500.000	1.6549E-04
7	17000.000	-1.0681E-03
8	17500.000	-2.5660E-03

Automatically adjust spectral range to span channels
 Automatically adjust spectral delta to sample channels

Minimum: 14000
 Maximum: 25000 Wavenumbers
 Delta: 500

Channel Spectral Responses

Relative Response

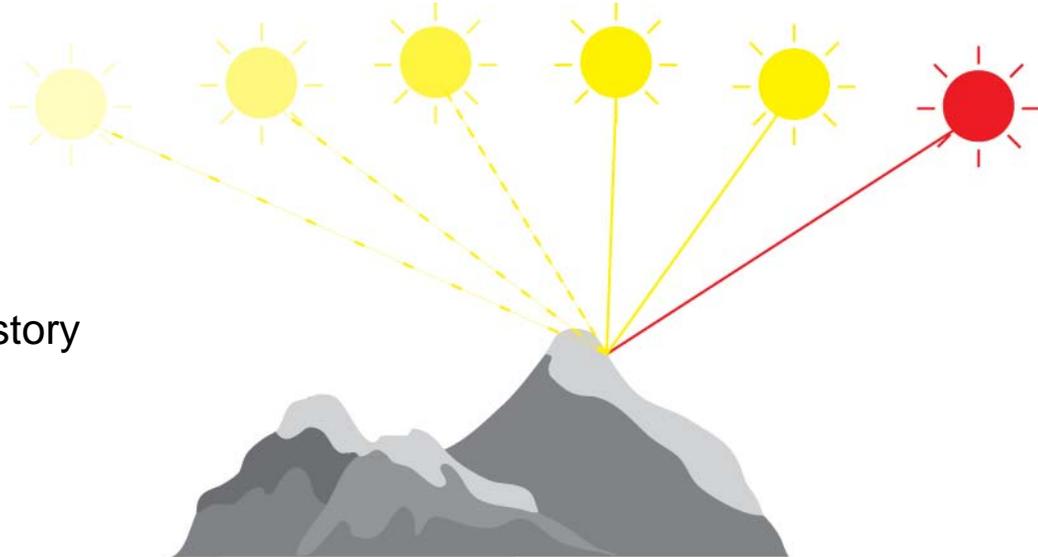
Frequency [wavenumbers]

OK Cancel

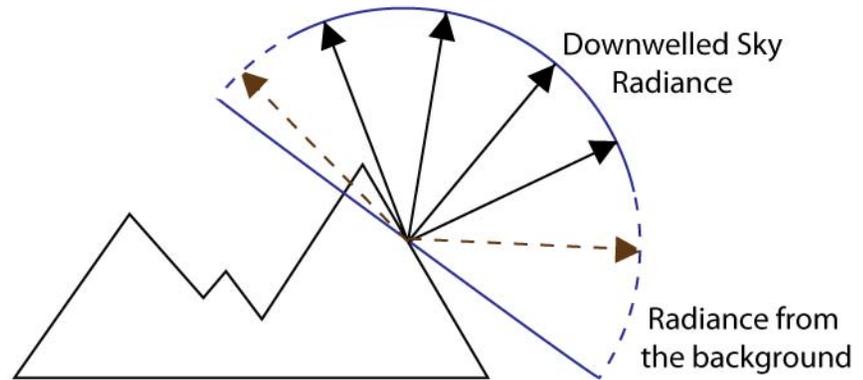


Ray Tracer Gathers Information for the Thermal and Radiometry Models

Sun Shadow History

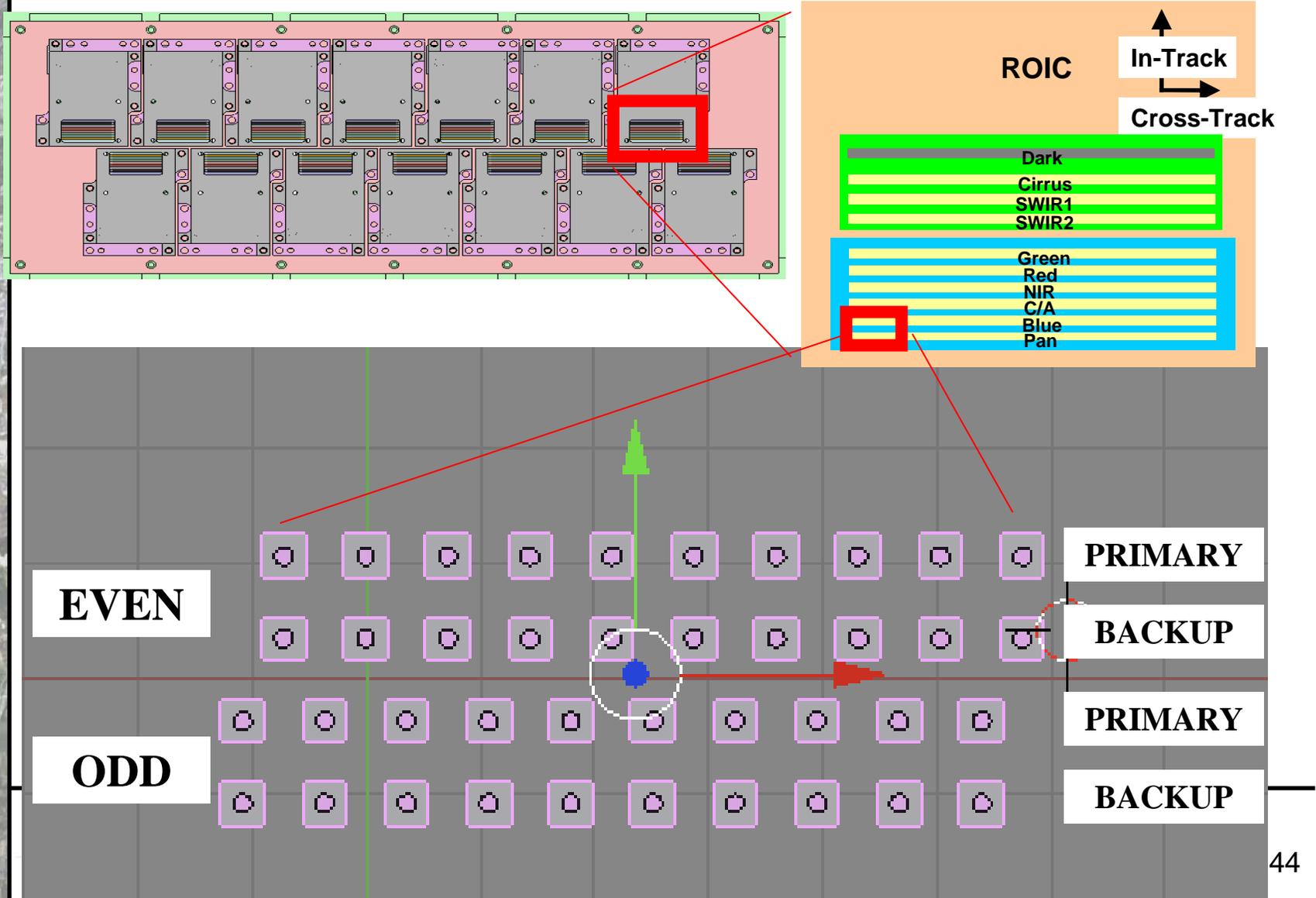


Radiance from Surround



Sensor Design

Blue Array Pixels Arrangement 36 μm detectors, 72 μm pitch (xy)



Sensor Design

Specifying Positions of Blue Odd Pixels Focal Plane 1

Detector Array Editor

Detector Array Geometry Editor

Detector Elements
 X Elements Y Elements

Detector Element Sizes
 X Element Size Y Element Size

Detector Element Gaps
 X Element Gap Y Element Gap

Array Centroid Offsets
 X Offset Y Offset

Options
 Mirror/Flip detectors about the X axis
 Mirror/Flip detectors about the Y axis

OK Cancel

Sensor Design

Array Centroid Offsets

Array Centroid Offsets

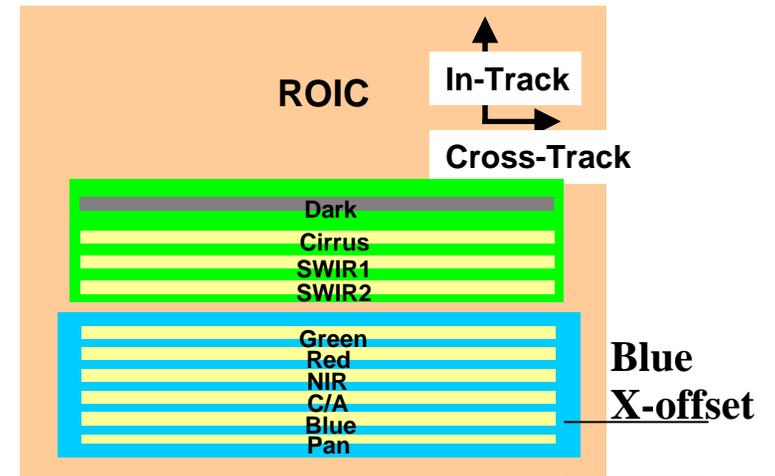
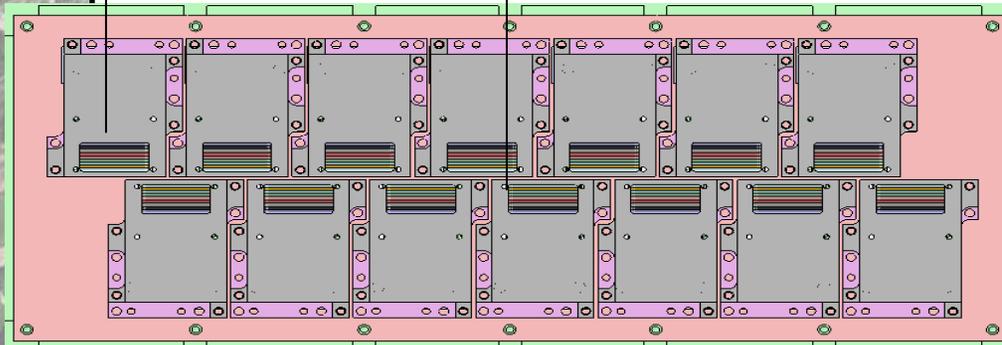
X Offset Y Offset

Options

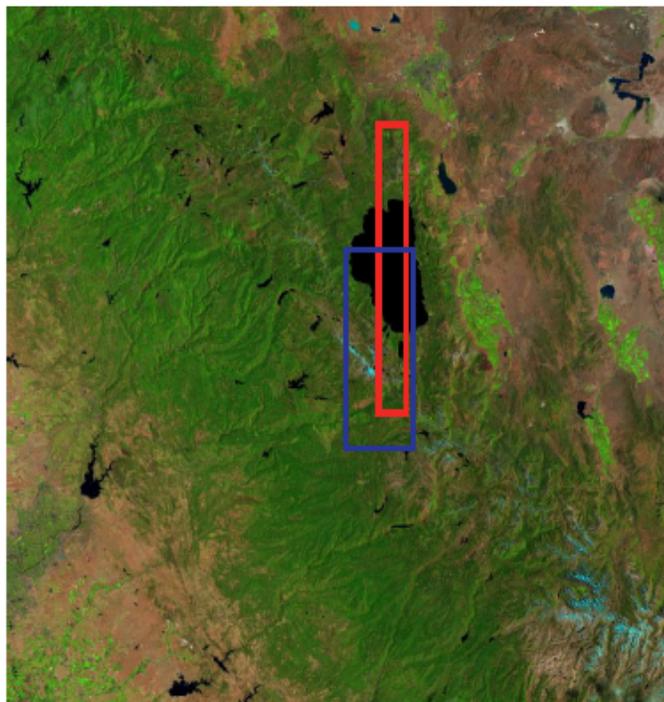
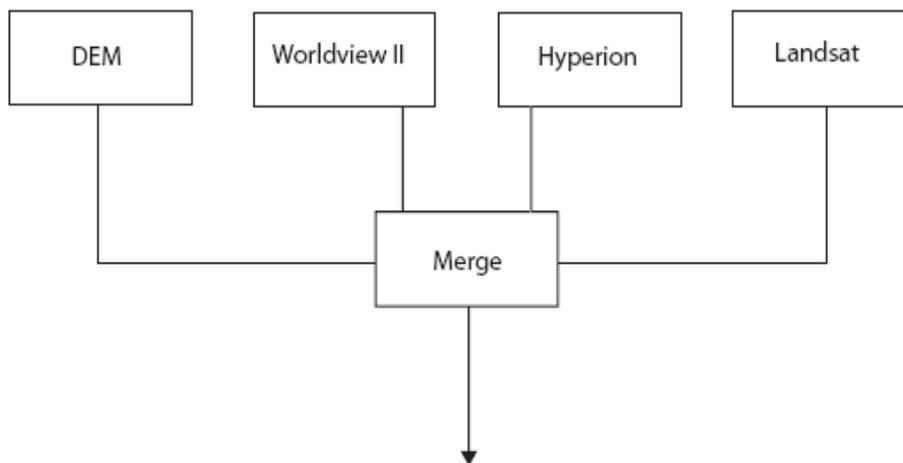
Mirror/Flip detectors about the X axis

Mirror/Flip detectors about the Y axis

**X-offset odd
or
X-offset even**

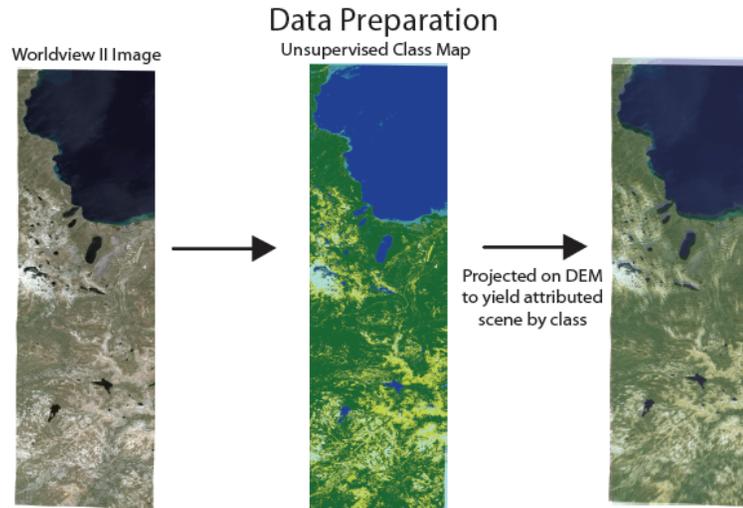


Virtual Scene Creation Approach

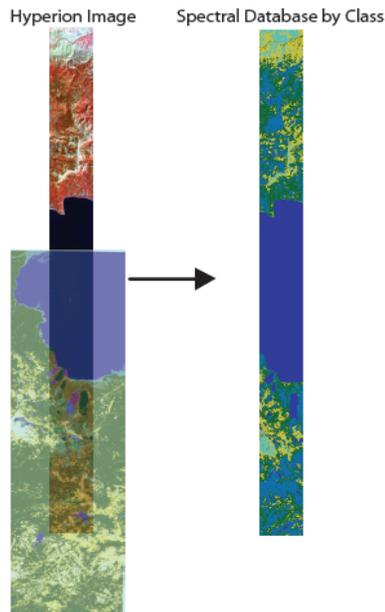




DIRSIG Scene Generation

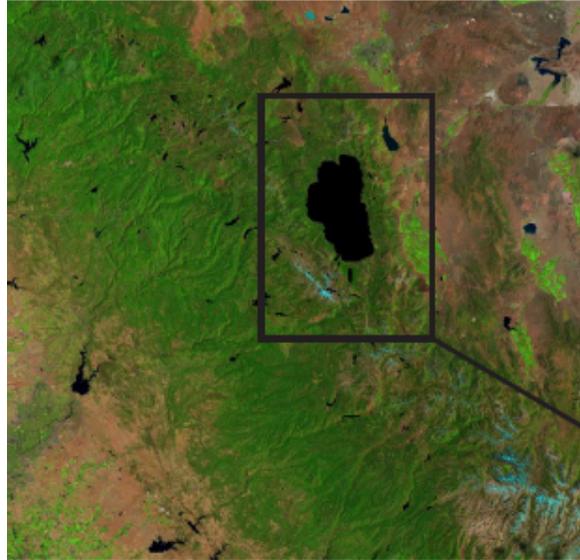


- Use fused data sets to establish a **virtual truth**
 - DEMs: scene geometry
 - Quickbird: MSI high spatial resolution Initial Landcover Class.
 - Hyperion: Spectral Resolution 196 bands 357 - 2576 nm
 - LANDSAT thermal texture
 - ASTER emissivity map
- Register QuickBird image to DEM
- Register Hyperion and ASTER to QB
- TIN DEM and format for use in DIRSIG

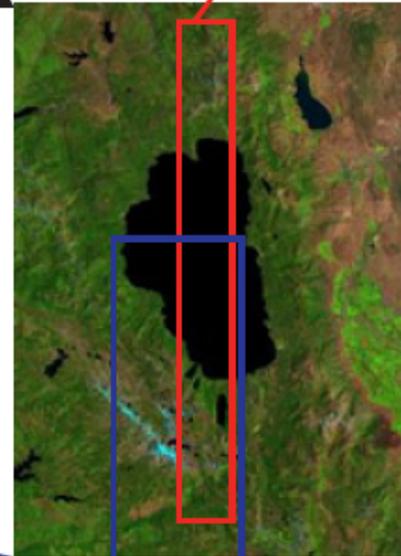


Target Site and Issues

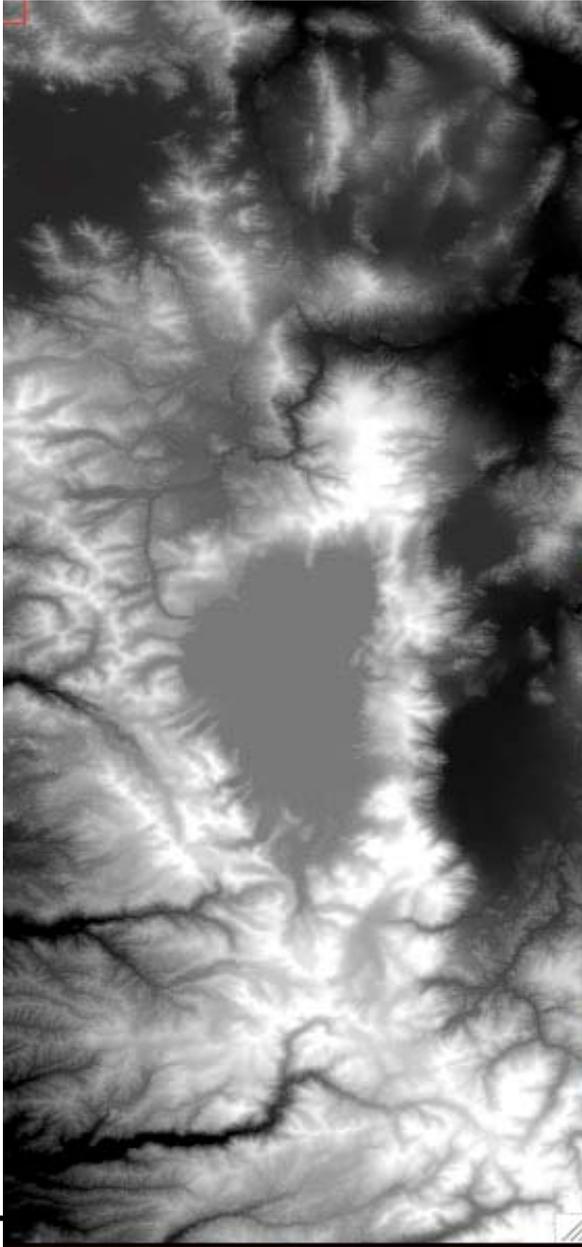
Landsat Image



Hyperion



Digital Globe



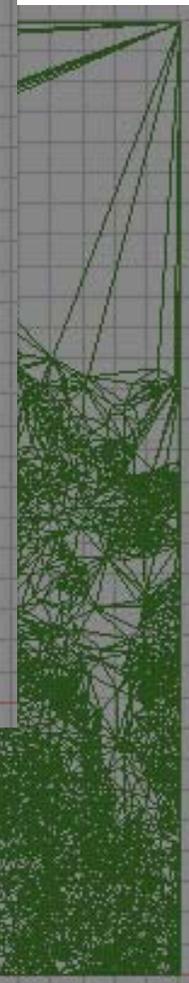
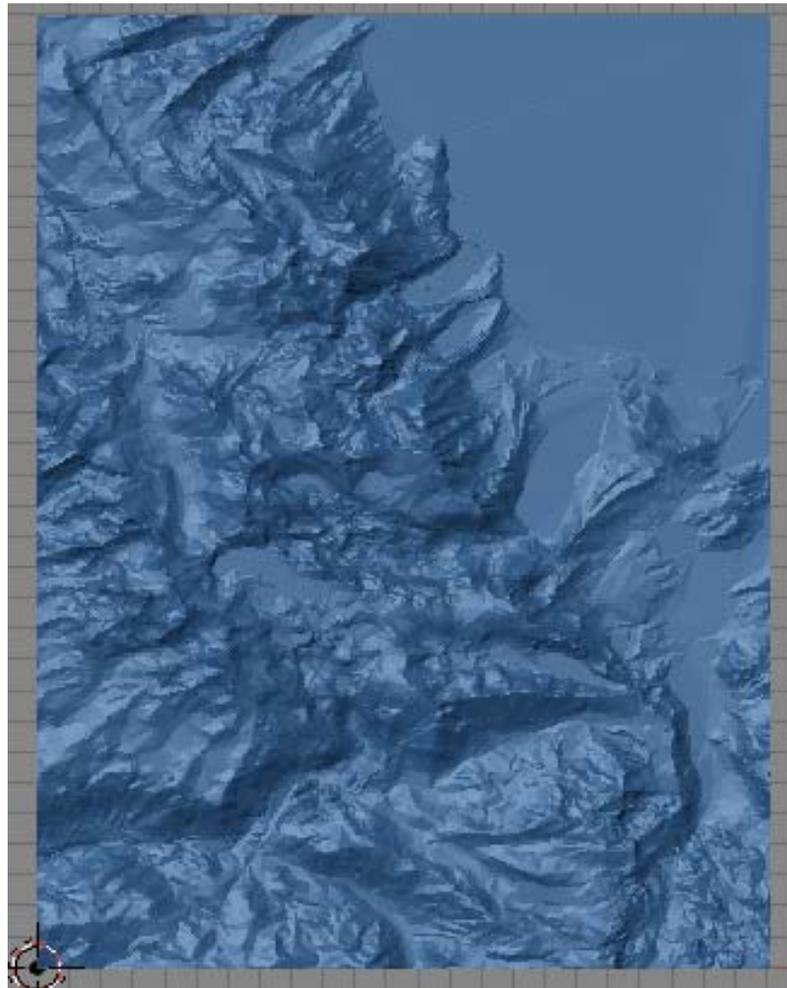
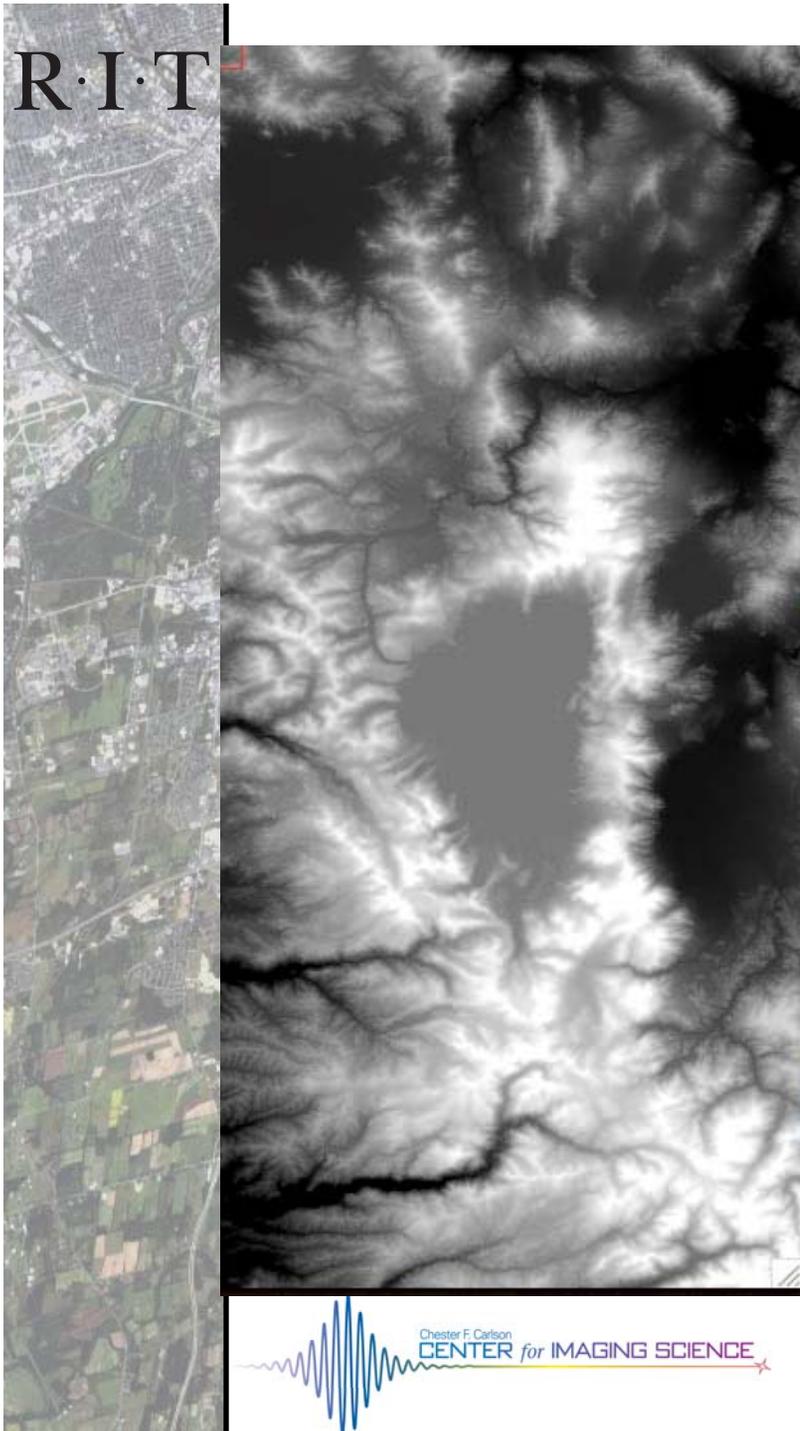
NED National Elevation Dataset Product

For Tahoe area 1/3 arc second is available
which corresponds to ~10m pixel or x,y
cell size =0.00009 degrees

Geographic properties:

- Geographic Lat/Long
- Horiz Datum NAD83
- Vert Datum NADV88 convert to WGS84
- Vert Units -meters
- Vert Accuracy - +/-7meters

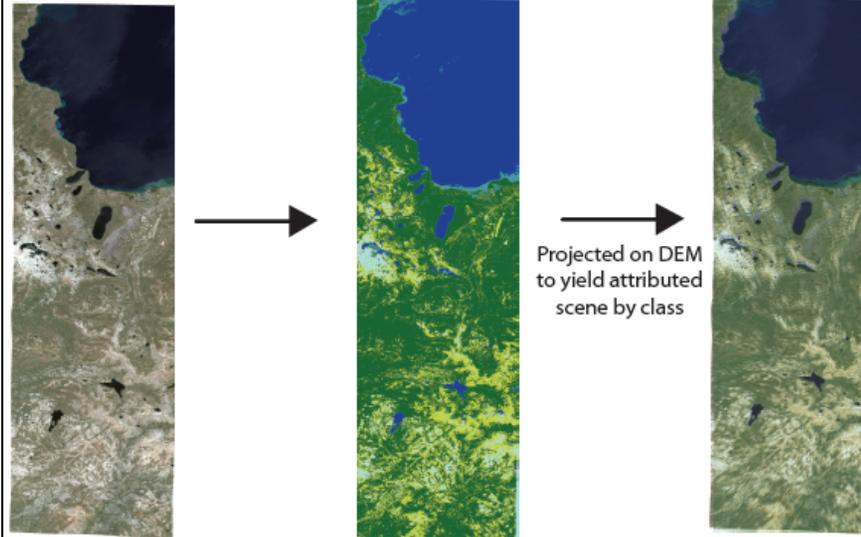
R·I·T





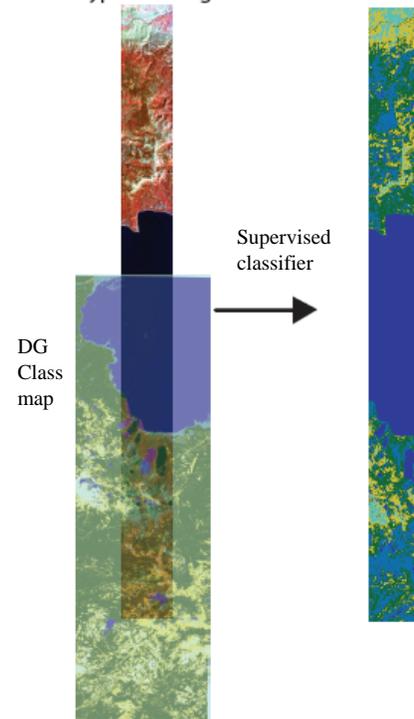
Data Preparation

Unsupervised Class Map

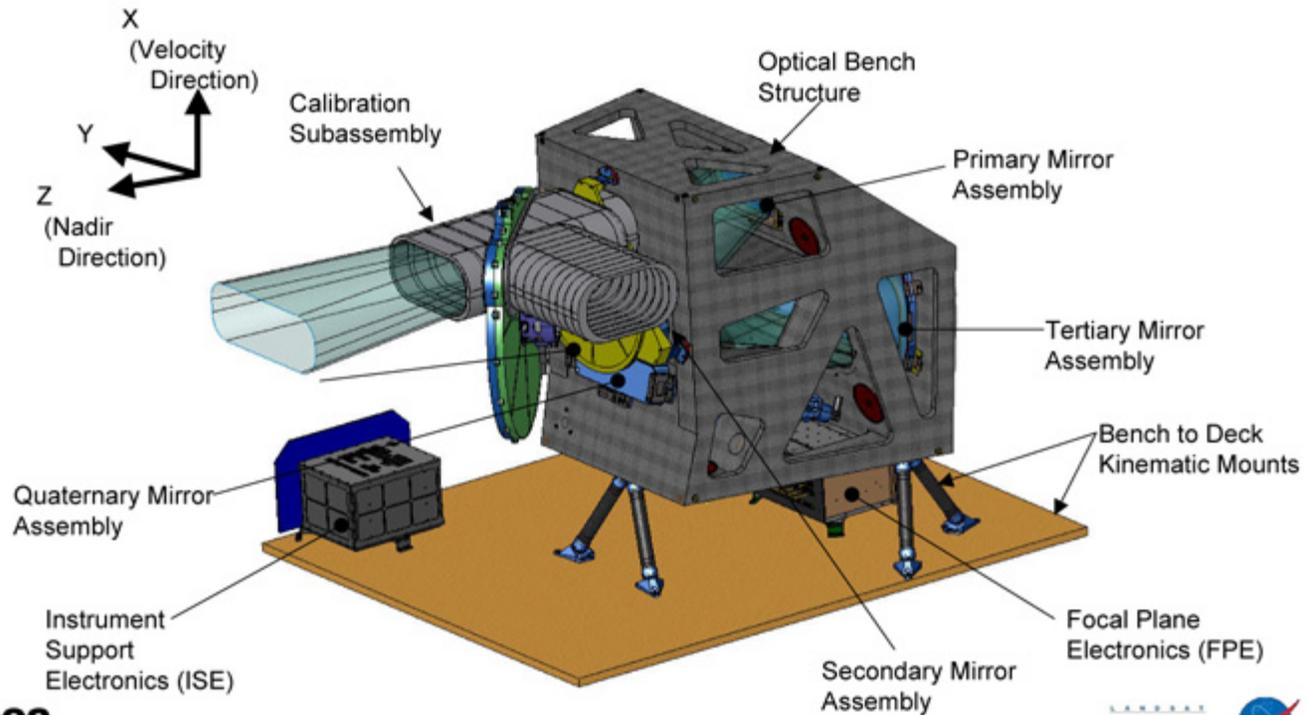


Hyperion Image

Hyperion class map

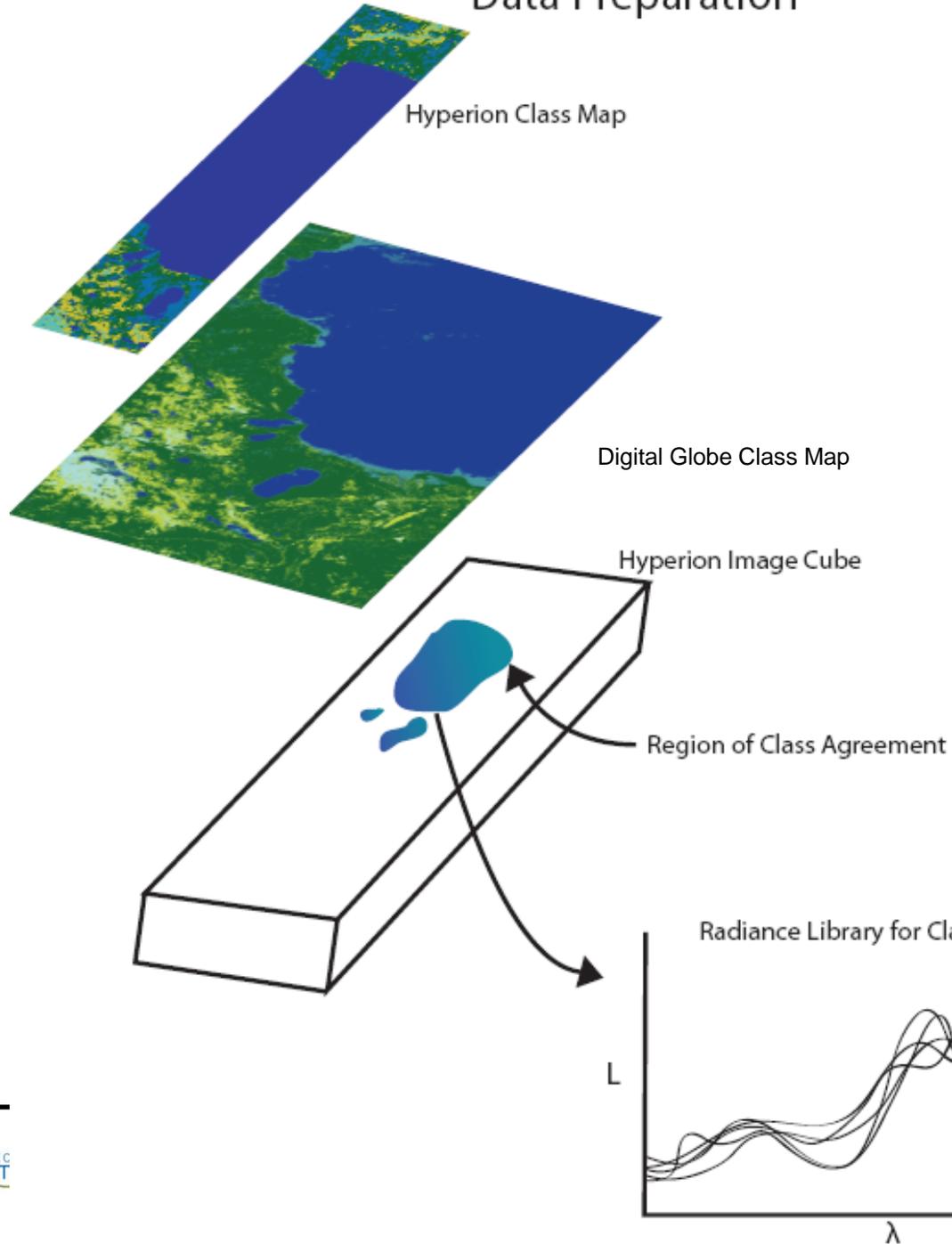


OLI Instrument Overview





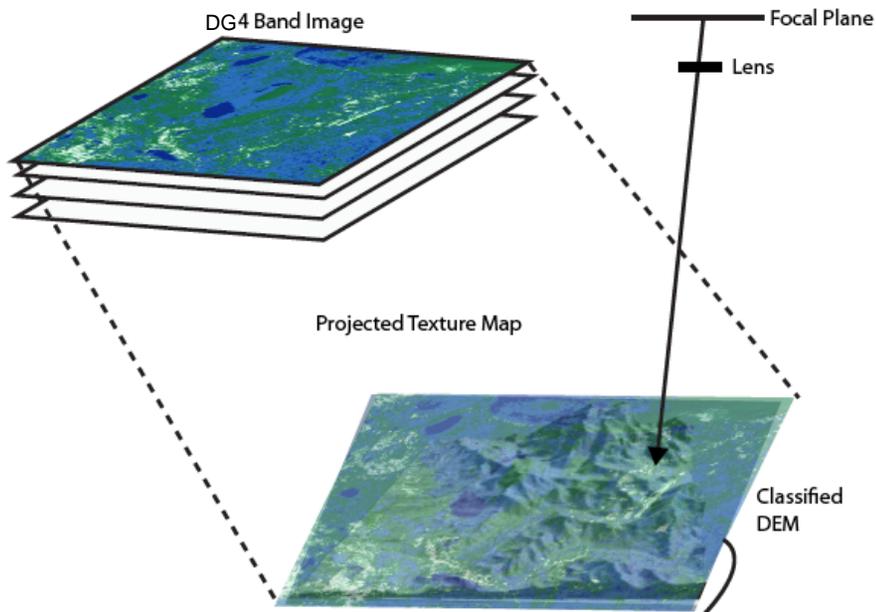
Data Preparation



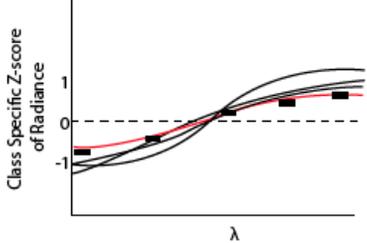
Build DIRSIG Inputs

- Run unsupervised classifier on QuickBird image to form large number of classes (e.g., 10's of classes)
- Project class map on DEM to generate attributed scene
- Project 4 band Quickbird image on class map to form texture image for spectral curve selection

Conceptual Implementation



Worldview II Z-score From Texture Map



Corresponding Radiance Curve for Sample Point

